

Dynamic problems for metamaterials: review of existing models and ideas for further research

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Abstract

Metamaterials are materials especially engineered to have a peculiar physical behaviour, to be exploited for some well-specified technological application. In this context we focus on the conception of general *micro-structured* continua, with particular attention to piezoelectromechanical structures, having a strong coupling between macroscopic motion and some internal degrees of freedom, which may be electric or, more generally, related to some *micro-motion*. An interesting class of problems in this context regards the design of *wave-guides* aimed to control wave propagation.

The description of the state of the art is followed by some hints addressed to describe some possible research developments and in particular to design optimal design techniques for bone reconstruction or systems which may *block* wave propagation in some frequency ranges, in both linear and non-linear fields.

Keywords: Metamaterials, micro-structured media, micropolar continuum, micromorphic continuum, variational principles

1. Introduction

At the very beginning of this paper the authors clarify that the use of the word *metamaterial* is intended as a synonym of microstructured continuum.

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One could question this choice, but, according to (Eringen, 2001), whenever a
5 continuum model is applicable then a suitable microstructural set of kinematical
descriptors can be determined which effectively describe the considered complex
system. Of course when wavelengths are small enough to interact with the
discrete microstructure then continuum models will not be applicable. We limit
ourselves, therefore, to deal with wave phenomena not influenced by the very
10 fine length micro-scale.

Metamaterials are materials which are designed to have *exotic* behaviour:
the concept has been first conceived for optical devices. Therefore, very often
one talks about mechanical metamaterials, when the exotic behaviour is limited
to mechanical effects, as *e.g.* very negative Poisson effects.

15 This paper is based on a really simple idea: construct a bridge between
two different cultural environments which address the same relevant problems.
Metamaterials are studied and conceived by physicists to tackle problems and
applications not yet considered in engineering sciences; at the same time the
community of continuum mechanics nearly completely ignores what physicists
20 devise and develop in the same field. This review intends to fill a gap in or-
der to stimulate a parallel development of the these theories and to near not
communicating scientific groups.

The mathematical formalism chosen thereafter is that preferred by physi-
cist, like Landau type variational principles, and the treated subjects are chosen,
25 in the opinion of the authors, from those considered nowadays more important
by applied mechanics.

The capability of continuum theories to describe the time evolution and the
deformation of the micro-structure of complex mechanical systems was recog-
nised in the very first formulations of continuum mechanics, as in the pioneering
30 work by Piola (Piola, 1846). He was lead by stringent physical considerations
to introduce higher gradients of displacement field, as necessary independent
variables, in the constitutive equation for the deformation energy of continu-
ous media. For a more modern interpretation of this subject refer to (Mindlin,
1964, 1965; Mindlin, Eshel, 1968; Toupin, 1962, 1964; Eringen, 1999, 2001, 2002;

35 [dell'Isola, Seppecher, 1995](#); [dell'Isola, Sciarra, Vidoli, 2009](#); [Sciarra, dell'Isola, Coussy, 2007](#); [Auffray, Bouchet, Brechet, 2009](#)).

However in a similar period, while Piola was producing his papers, Cauchy and Poisson obtained a description, with a very elegant and effective format, for continuum mechanics in which:

40 i) the displacement from a reference configuration is the only kinematic descriptor;

ii) the crucial conceptual tool is Cauchy stress which is constitutively related only to the first gradient of displacement;

45 iii) the crucial postulates are those concerning balance of mass, linear and angular momentum and, when necessary, energy.

The Cauchy-Poisson format is usually very effective to describe the mechanical behaviour of a very wide class of natural and also artificial materials. Nevertheless, when considering materials with very well-organised microstructures, subjected to particular loads and/or boundary conditions, Cauchy's continuum 50 theory may not be accurate. This is the case of some engineered materials having high contrast of material properties ([Alibert, Seppecher, dell'Isola, 2003](#); [dell'Isola, Rosa, Woźniak, 1997, 1998](#); [Ferretti et al., 2013](#); [Pideri, Seppecher, 1997](#); [Camar-Eddine, Seppecher, 2002, 2003](#); [Contro, Poggi, Cazzani, 1988](#)) or for some natural materials with highly heterogeneous hierarchical microstructures 55 ([Buechner, Lakes, 2003](#)). In all these cases, the introduction of more sophisticated models is mandatory in order to satisfactorily catch the features of the mechanical behaviour of such complex materials.

Many and unexpected effects on wave propagation can be mathematically predicted and described in the study of continua with micro-structures ([Manktelow, Leamy, Ruzzene, 2013a,b](#); [Narisetti, Ruzzene, Leamy, 2011, 2012](#); [Placidi et al., 2013](#); [Rosi, Giorgio, Eremeyev, 2013](#); [Rosi, Madeo, Guyader, 2013](#); [dell'Isola, Madeo, Placidi, 2012](#); [Eremeyev, 2005](#); [Altenbach et al., 2010](#)).

The intent of this review is to indicate the importance of the aforementioned effects and to direct the investigation towards those among them having 65 engineering relevance.

We want to underline that some mathematical results, as those in [Ghiba et al. \(2013\)](#) and [Neff et al. \(2013\)](#), together with the analysis developed in the framework of continuum mechanics ([dell’Isola, Madeo, Placidi, 2012](#); [Placidi et al., 2013](#)), can produce interesting hints useful to investigate on exotic effects, *i.e.* unconventional dynamic behaviours, which can be exploited in engineering applications. For instance, the *singular* model studied in [Ghiba et al. \(2013\)](#) attracted the attention of the authors because of the difficulties to define some technical upper bounds for the solutions of formulated partial differential equations (PDEs). However the singularity pointed out by the mathematical difficulties is an indication of some peculiarities of this case of micro-morphic, Mindlin-type, micro-structured continua. These peculiarities, afterwards studied and not yet completely described in [Neff et al. \(2013\)](#), promise interesting and probably important applications.

In [Mindlin \(1964\)](#) Mindlin excludes from his analysis the metamaterials considered in [Ghiba et al. \(2013\)](#) and [Neff et al. \(2013\)](#) since their deformation energy is not definite positive as a function of the defined deformation measures: with this meaning the word *singular* used in a previous sentence should be interpreted.

The challenge consist in using mathematics, continuum modelling, numerical simulations techniques and experiments to determine those material properties which may play a significant role in future technological advances.

In the section dealing with the research perspectives, possible developments are imagined from an applicative point of view.

The literature about metamaterials is enormous and in this paper only some instances are cited.

2. A Matter of Principle

We assume that every physical phenomenon can be described by means of a maybe modified or improved version of the Principle of Least Action ([Hellinger, 1913](#)). The whole mathematical content of the present work actually is re-

duced to a general formulation of this Principle and on a series of examples, in which particular Lagrangian functions and, possibly, particular Hamilton-Rayleigh dissipation functionals are specified to deal with a particular class of phenomena.

2.1. The Principle of Least Action

As discussed *e.g.* in [dell'Isola, Placidi \(2012\)](#), to formulate a mathematical model following the spirit of Lagrange one has to:

1. single out the kinematical descriptors which describe the state of the physical system;
2. choose the set of admissible motions for the system under description;
3. exert the *physical intuition* to find the right *Action Functional* whose minima are exactly the searched motions.

A configuration is the mathematical object used to model the state of the system: the set of possible configurations will be denoted by C . The only possible way for labelling a configuration is to find the values of the kinematical descriptors corresponding to it.

The motion is the mathematical model describing the evolution of the system: it is a C -valued function defined on time interval (t_0, t_f) ; the set of all admissible motions will be denoted by M . Of course one has to assume some regularity properties for the motions in M . For instance: to exclude impulsive motions, the regularity hypothesis requires that the second time derivative of C -valued function exists.

The action is a real-valued function, defined on M : for traditional reasons and also to avoid to repeat too often the word function, the action is said to be a functional: that is a function defined in a set of functions.

Finally, to use the Principle of Least Action sometimes it is useful to:

1. find the Euler-Lagrange conditions which are consequence of the postulated Least Action Principle;
2. interpret these conditions on a physical ground.

In epochs in which the only method for getting some previsions about the be-
 125 haviour of a physical system was to find a more or less explicit solution of some
 system of differential equations, the determination of Euler-Lagrange minimality
 conditions supplied the fundamental calculation tool for the applied scientists.
 This is not the case nowadays considering the systematic use of computers in
 science. It has become progressively more important to determine the numerical
 130 integration scheme to adopt in order to predict the model behaviour, in terms
 of the postulated Action Functional: therefore the role of Euler-Lagrange equa-
 tions has become less important. However, the presented integration by parts
 procedure remains important for determining the boundary conditions.

2.2. Lagrangian Action Functionals: technical details

135 In our presentation we follow more or less closely [Landau, Lifshitz \(1975, 1976, 1977\)](#).

Let $\Psi_\sigma(x_\mu)$ be any set of n tensor fields defined on \mathbb{R}^m , σ being a multi-index
 and $\mu = 1, 2, \dots, m$. We do not want to limit ourselves to three-dimensional or
 four-dimensional, including time, spaces for defining the fields Ψ_σ . So *e.g.*, when
 140 dealing with shells we need bi-dimensional domains for Ψ_σ and when dealing
 with beams we need one-dimensional domains.

If we define the Lagrangian density as:

$$\mathfrak{L}\left(x_\mu, \Psi_\sigma, \frac{\partial \Psi_\sigma}{\partial x_\mu}\right) \quad (1)$$

then we can introduce the Action Functional as

$$\mathfrak{A} = \int_T \mathfrak{L}\left(x_\mu, \Psi_\sigma, \frac{\partial \Psi_\sigma}{\partial x_\mu}\right) \quad (2)$$

where T is a hyper-volume in the m -dimensional space determined by the x_μ .

We remark that this is only a possible choice of Action Functional: however
 it seems to be general enough to formulate all the models which were conceived
 145 up to now.

2.3. Variation of the Action Functional

We now consider small variations $\varepsilon\eta_\sigma(x_\mu)$ of the considered fields $\Psi_\sigma(x_\mu)$:

$$\tilde{\Psi}_\sigma(x_\mu) = \Psi_\sigma(x_\mu) + \varepsilon\eta_\sigma(x_\mu) \quad (3)$$

where the $\eta_\sigma(x_\mu)$ are any set of linearly independent functions of the x_μ which vanish on the part $\partial_d T$ ($\partial_d T \subseteq \partial T$) of the boundary ∂T of the hyper-volume T ,
 150 on which the kinematical condition are prescribed. The variation of the action functional can then be computed as:

$$\Delta\mathfrak{A} = \int_T \mathfrak{L} \left(x_\mu, \tilde{\Psi}_\sigma, \frac{\partial \tilde{\Psi}_\sigma}{\partial x_\mu} \right) - \int_T \mathfrak{L} \left(x_\mu, \Psi_\sigma, \frac{\partial \Psi_\sigma}{\partial x_\mu} \right) \quad (4)$$

The computation of the variation of the Action Functional now proceeds as follows:

$$\begin{aligned} \Delta\mathfrak{A} &= \int_T \mathfrak{L} \left(x_\mu, \Psi_\sigma + \varepsilon\eta_\sigma, \frac{\partial \Psi_\sigma}{\partial x_\mu} + \varepsilon \frac{\partial \eta_\sigma}{\partial x_\mu} \right) \\ &\quad - \int_T \mathfrak{L} \left(x_\mu, \Psi_\sigma, \frac{\partial \Psi_\sigma}{\partial x_\mu} \right) + O(\varepsilon^2) \end{aligned} \quad (5)$$

Which, with a slight abuse of notations, can be written at the first order in ε as:

$$\delta\mathfrak{A} = \varepsilon \int_T \sum_\sigma \left[\frac{\partial \mathfrak{L}}{\partial \Psi_\sigma} \eta_\sigma + \sum_{\mu=1}^m \frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_\mu)} \frac{\partial \eta_\sigma}{\partial x_\mu} \right] \quad (6)$$

Integrating by parts and recalling that η_σ vanish on S it is easy to get:

$$\begin{aligned} \delta\mathfrak{A} &= \varepsilon \int_T \sum_\sigma \eta_\sigma \left\{ \frac{\partial \mathfrak{L}}{\partial \Psi_\sigma} - \sum_{\mu=1}^m \frac{\partial}{\partial x_\mu} \left[\frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_\mu)} \right] \right\} \\ &\quad + \varepsilon \int_{\partial T / \partial_d T} \sum_\sigma \eta_\sigma \sum_{\mu=1}^m \frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_\mu)} N_\mu \end{aligned} \quad (7)$$

where $\partial T / \partial_d T$ is the symmetric difference between ∂T and $\partial_d T$ and N_μ is the external unit normal of $\partial T / \partial_d T$.

Imposing the stationarity condition

$$\delta\mathfrak{A} = 0 \quad (8)$$

the arbitrariness of η_σ gives, for any σ :

$$\frac{\partial \mathfrak{L}}{\partial \Psi_\sigma} - \sum_{\mu=1}^m \frac{\partial}{\partial x_\mu} \left[\frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_\mu)} \right] = 0, \quad \forall x_\mu \in T \quad (9)$$

$$\sum_{\mu=1}^m \frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_\mu)} N_\mu = 0, \quad \forall x_\mu \in \partial T / \partial_d T \quad (10)$$

In the case of a discontinuity material surface Σ , with unit normal N_μ , the (10) have to be completed by

$$\sum_{\mu=1}^m \left[\left[\frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_\mu)} \right] \right] N_\mu = 0, \quad \forall x_\mu \in \Sigma \quad (11)$$

155 where $[[(\cdot)]]$ is the jump of (\cdot) across the surface Σ . These equations are known as the Euler-Lagrange equations corresponding to the considered Lagrangian density.

2.4. The Space-Time Case (\mathbb{R}^4)

Let us now consider the particular case in which $m = 4$. This case commonly corresponds to the case $x_\mu = (x_1, x_2, x_3, t)$. We have that $\eta_\sigma(x_\mu)$ are any set of linearly independent functions of x_μ which vanish on the boundary of time type domain,

$$\eta_\sigma(x_1, x_2, x_3, t_0) = \eta_\sigma(x_1, x_2, x_3, t_1) = 0$$

and on the part $\partial_d V$ of the boundary ∂V of the volume V , on which the kinematical conditions are fixed,

$$\eta_\sigma(x_1, x_2, x_3, t) = 0, \quad \forall (x_1, x_2, x_3) \in \partial_d V, \quad \forall t \in [t_0, t_1].$$

It is easy to show that in this particular case equation (7):

$$\begin{aligned} \delta \mathfrak{A} = & \varepsilon \int_{t_0}^{t_1} dt \int_V \sum_\sigma \eta_\sigma \left[\frac{\partial \mathfrak{L}}{\partial \Psi_\sigma} - \sum_{k=1}^3 \frac{\partial}{\partial x_k} \left(\frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_k)} \right) - \frac{\partial}{\partial t} \left(\frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial t)} \right) \right] dV \\ & + \varepsilon \int_{\partial V / \partial_d V} \sum_\sigma \eta_\sigma \sum_{k=1}^3 \frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_k)} N_k + \int_\Sigma \sum_\sigma \left[\left[\eta_\sigma \sum_{k=1}^3 \frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_k)} \right] \right] N_k \end{aligned} \quad (12)$$

The stationarity $\delta\mathfrak{A} = 0$ of the action implies, for any $\sigma = 1, 2, \dots, n$,

$$\frac{\partial \mathfrak{L}}{\partial \Psi_\sigma} - \sum_{k=1}^3 \frac{\partial}{\partial x_k} \left(\frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_k)} \right) - \frac{\partial}{\partial t} \left(\frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial t)} \right) = 0, \quad \forall x_k \in V \quad (13)$$

$$\sum_{k=1}^3 \frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_k)} N_k = 0, \quad \forall x_\mu \in \partial V / \partial_d V \quad (14)$$

$$\sum_{k=1}^3 \left[\left[\frac{\partial \mathfrak{L}}{\partial (\partial \Psi_\sigma / \partial x_k)} \right] \right] N_k = 0, \quad \forall x_\mu \in \Sigma \quad (15)$$

160 Which are the standard Euler-Lagrangian equations. We show below how to generalise (15) when Σ can freely move.

2.5. Rayleigh-Hamilton Principle

Least Action Principle is not easily adapted to deal with dissipative systems (dell'Isola, Placidi, 2012). A chance to overcome the related difficulties consists in postulating the Rayleigh-Hamilton Principle. It is based on the choice of a
165 dissipation functional which is a functional of the velocities along the motions. The first variation with respect to velocities of this functional has to be calculated on the first variations of motions and to be equated to the first variation of Action Functional, to get the searched equations of motions.

One can introduce a dissipation functional of the type

$$\mathfrak{D} = \int_T \mathfrak{R} \left(x_\mu, \dot{\Psi}_\sigma, \frac{\partial \dot{\Psi}_\sigma}{\partial x_\mu} \right) \quad (16)$$

170 where \mathfrak{R} is the Rayleigh potential density.

The first variation of this functional with respect to $\dot{\Psi}_\sigma$ is a linear functional of the variation of its argument. This linear functional has to be calculated in η_σ and equated to $\delta\mathfrak{A}$ in equation 8 to produce the final evolution equations. Remark that the conditions 9 and 10, 11 are correspondingly modified with the
175 introduction of derivatives of \mathfrak{R} .

2.6. Principle of Virtual Work and Principle of Least Action

Sometimes it is believed that postulation methods based on the Principle of Virtual Work are much different from those recalled in the previous subsections. This is not indeed the case, as there is a strict relationship between them.

The Principle of Least Action, when formulated for action functionals admitting first differentials, can be regarded as a particular form of the Principle of Virtual Work. If one can decompose the action into its internal, external and inertial parts, as follows

$$\mathfrak{A} = \mathfrak{A}^{int} + \mathfrak{A}^{ext} + \mathfrak{A}^{ine} \quad (17)$$

then

$$\delta\mathfrak{A} = 0 \iff \delta\mathfrak{A}^{int} + \delta\mathfrak{A}^{ext} + \delta\mathfrak{A}^{ine} = 0 \quad (18)$$

Identifying the decomposed actions with corresponding powers

$$\delta\mathfrak{A}^{int} = \mathfrak{P}^{int} \quad \delta\mathfrak{A}^{ext} = \mathfrak{P}^{ext}, \quad \delta\mathfrak{A}^{ine} = \mathfrak{P}^{ine} \quad (19)$$

we get

$$\mathfrak{P}^{int} + \mathfrak{P}^{ext} + \mathfrak{P}^{ine} = 0 \quad (20)$$

180 which is the standard form of Principle of Virtual Power, equivalent to the Principle of Virtual Work when action functionals admit first differentials, as mentioned.

3. State of the Art

In general, metamaterials are artificial materials engineered by assembling
 185 multiple individual elements, usually arranged in (quasi-)periodic patterns, in order to show very peculiar and specific physical properties, due to their designed substructures and not to their composition.

It may be remarked that the expression *metamaterial* and the early studies
 190 in this field were primarily diffused among the scientific area dominated by physicists: so first examples of designed metamaterials had very peculiar electromagnetic, optical or thermodynamic properties. Subsequently, the so-called *mechanical* metamaterials received the attention of scientists: *e.g.* in [Xu et al. \(1999\)](#), [Engheta, Ziolkowski \(2006\)](#) and [Christensen, de Abajo \(2012\)](#) mechanical exotic properties were conceived and exploited. These materials may also

195 show interesting coupling phenomena with several thermodynamic or electro-
magnetic unconventional properties (Berezovski, Maugin, 2005a,b; Berezovski,
Engelbrecht, Peets, 2010; Berezovski, Engelbrecht, Berezovski, 2011; Berezovski,
Engelbrecht, Maugin, 2011; Maugin, Muschik, 1994a,b). These coupling phe-
nomena deserve a great attention as they can be fruitfully developed.

200 We focus on a small part of the literature on metamaterial: we are interested
in so-called *micro-structured metamaterials*, having a behaviour expressible with
continuum models in which along with the placement field other kinematic de-
scriptors are employed. In the rest of this paper we refer to them simply as
metamaterial, but otherwise specified. In this context we mention the classical
205 works by Eringen (1999, 2001, 2002), Eringen, Suhubi (1964a,b), Sedov (1968,
1972), Toupin (1962, 1964) and Bleustein (1967), among those which merit
considerable attention.

The idea underlying the theory of micro-structured continua is simple: the
complexity of the structure of some materials or living tissues (Federico, Herzog,
210 2008b,c; Federico, Gasser, 2010; Madeo, Lekszycki, dell’Isola, 2011; Federico,
Grillo, 2012; Lekszycki, dell’Isola, 2012) or reinforcements (Nadler, Papadopoulos,
Steigmann, 2006; Ferretti et al., 2013) can be still described by considering
field theories, but with the addition of tensorial fields to account for the time
evolution of micro-structures.

215 In the formulation of these new models, the problem of determining the most
suitable evolution equations arises once the kinematic parameters are selected:
in our opinion the most effective method is based on the formulation of a suitable
variational principle, as in the references stemming from the fundamental work
by Lagrange (Lagrange, 1788), *e.g.* Auffray et al. (2013), Daher, Maugin (1986),
220 Epstein (2010), Cazzani, Lovadina (1997) Germain (1973a,b), Green, Rivlin
(1964a), Kroner (1968), Maugin (2013), Sedov (1968), Toupin (1962, 1964) and
Bedford (1985).

Indeed, variational methods have the very positive feature to produce well-
posed mathematical problems, where the corresponding energy and dissipation
225 functionals are well-behaving, and to lead more easily to the formulation of

effective numerical integration schemes.

Of course, in formulation and use of these *enhanced* field theories, the adoption of Ricci and Levi-Civita indicial notation (Ricci-Curbastro, Levi-Civita, 1900; Lebedev, Cloud, Eremeyev, 2010) and absolute tensor calculus cannot
 230 be avoided and it is simply not conceivable to tackle these theories with a component-wise notation. In this context, the differential geometry plays an essential role as it already does in standard continuum mechanics (Epstein, 2010; Epstein, Segev, 1980; Segev, 1986, 2000; Spivak, 1979).

3.1. Cosserat and micromorphic continua

235 About fifty years later Piola's main contributions, his ideas were developed. A Lagrangian density example for Piola-type media is

$$\begin{aligned} \mathfrak{L}(\nabla \mathbf{u}, \nabla \nabla \mathbf{u}, \dot{\mathbf{u}}) = & \frac{1}{2} \rho \|\dot{\mathbf{u}}\|^2 + \\ & - \left(\mu \|\text{sym } \nabla \mathbf{u}\|^2 + \frac{\lambda}{2} (\text{tr } \nabla \mathbf{u})^2 + \frac{\alpha}{2} \|\nabla \nabla \mathbf{u}\|^2 \right) \end{aligned} \quad (21)$$

where ρ is the mass density, μ and λ are the Lam parameters, α is the second gradient stiffness and \mathbf{u} is the displacement field.

The Cosserat brothers were among the first authors who complemented, with
 240 additional independent kinematic fields, the standard kinematics constituted by a placement field. According to them, these fields are Euler angles, representing rigid rotations of the microstructure with respect to the overall continuum local displacement. Cosserat contributions (Cosserat brothers, 1909) were underestimated for other fifty years and only starting from 1960 a group constituted by
 245 notable scientific personalities as Mindlin, Green and Rivlin, Toupin, Eringen and Germain (Green, Rivlin, 1964a,b,c, 1965; Mindlin, 1964, 1965; Toupin, 1962, 1964; Eringen, 1999, 2001, 2002; Eringen, Suhubi, 1964a,b; Germain, 1973a,b) managed to establish, yet with some resistances, the validity of Cosserat's point of view.

250 Actually, Cosserat's approach can be further generalised including in macroscopic models, along with micro-rotations, also micro-stretches, micro-strains or

concentrated micro-deformations, so introducing the so-called micro-structured or micropolar or micromorphic continuum models (Erofeyev, Potapov, 1993; Potapov, Pavlov, Maugin, 1999; Erofeyev, Pavlov, Leontiev, 2013). These can
255 be formulated through a postulation process based on the principle of least action (Auffray et al., 2013) or on the principle of virtual works (Maugin, Metrikine, 2010; Maugin, 2013). Later on, alternative postulation procedures, based on generalised balance laws, have been also attempted (Eringen, 1999, 2001).

260 Indeed, as already remarked in Piola (1846), it is rather unlikely to achieve a standard Cauchy continuum starting from a discrete system with a multi-length-scale microstructure.

The evolution of non purely mechanical phenomena can be described within the framework of micromorphic continuum theory: in this context we refer *e.g.*
265 to phenomena observed in piezoelectromechanical structures (Vidoli, dell’Isola, 2000, 2001) where also electromagnetic descriptors are necessary to characterise the kinematics of the system.

The micromorphic model, as a natural generalisation of the Cosserat approach, has also mainly been studied in its linearised version. Existence results for the nonlinear static setting are quite recent (Neff, 2006c; Neff, Forest,
270 2007). There are manifold connections to models of gradient continua and elasto-plasticity, still awaiting closer mathematical inspection (Neff et al., 2009; Klawonn, 2011).

It has to be explicitly remarked that Piola’s and Cosserat’s models can be
275 reconciled, *i.e.* Cosserat reduced to Piola, introducing internal constraints and Lagrange multipliers as clearly stated in (Bleustein, 1967): the second gradient materials can be seen as a particular limit case of the micromorphic media as they can be obtained from micromorphic ones constraining the micromorphic tensor to be equal to the classical strain tensor. Actually one can get Piola’s
280 deformation energies depending on higher gradients of displacement, as a limit of many different, physically non-equivalent, more detailed micromorphic models.

To formulate three-dimensional Cosserat theories, the framework built to

construct Cauchy's model needs to be deeply modified and in particular the concept of stress needs to be revisited (Neff, 2006a,b; Neff, Jeong, 2009; Pietraszkiewicz, 285 Eremeyev, 2009). This last difficulty is a serious conceptual one, as Cauchy paradigm has become a mental habitude, or even a natural *belief*, for many engineers and material scientists: as a matter of fact, in the opinion of the authors, the first scientists who managed to get rid of it were actually physicists.

A Lagrangian density example for Cosserat-type media can be expressed

$$\begin{aligned} \mathfrak{L}(\nabla \mathbf{u}, \mathbf{Q}, \dot{\mathbf{u}}, \dot{\mathbf{Q}}) &= \frac{1}{2} \rho \|\dot{\mathbf{u}}\|^2 + \frac{1}{2} \eta \|\dot{\mathbf{Q}}\|^2 + \\ &- \left(\mu_e \|\text{sym } \nabla \mathbf{u}\|^2 + \frac{\lambda_e}{2} (\text{tr } \nabla \mathbf{u})^2 + \mu_c \|\text{skew } (\nabla \mathbf{u}) - \mathbf{Q}\|^2 + \frac{\alpha}{2} \|\text{Curl } (\mathbf{Q})\|^2 \right) \end{aligned} \quad (22)$$

290 where $\nabla \mathbf{u}$ is the gradient of displacement field and the micro-rotation tensor \mathbf{Q} is a second order tensor associated to the microstructure rotations, ρ is the density per unit of macro volume of the material, η is the micro-density and μ_e, λ_e, μ_c and α are elastic coefficients assumed to be constant.

The Cosserat brothers never proposed a linearisation of their intrinsically 295 nonlinear theory, neither elaborated on any specific constitutive law. The re-discovery of the Cosserat approach in the second half of the last century was mainly restricted to a linearisation of their equations. However, more than 50 years later, no material has been conclusively shown to be a Cosserat material yet. For the linear Cosserat model and its mathematical complexity we refer to 300 the discussion in Neff, Jeong (2009) and Neff, Jeong, Fischle (2010). Devoid of any physical meaning, the linear Cosserat approach may be used as a regularisation for otherwise ill-posed problems, *e.g.* in elasto-plasticity (Neff, Wieners, 2003; Neff, Chęmiński, 2005).

The problems with the linear Cosserat model, referred to above, are all 305 connected to the question of how the Cosserat rotations and the macroscopic rotations are locally coupled. This coupling is governed in the linearised model by the Cosserat couple modulus μ_c , which penalises the quadratic difference between micro- and macro-rotation. Its numerical value is under constant debate.

We run into the role of that modulus later on, again in conjunction with the
310 micromorphic models.

A new turn for the Cosserat model can be found in the Neff's work. With
a closer look to the original nonlinear Cosserat model, he provided the first
existence proof in the geometrically nonlinear case and investigated some phys-
ical applications. As it turned out, the question of how to couple micro- and
315 macro-rotations in the nonlinear model has different answers. One may use the
already known *linear* coupling, relying on the introduction and determination of
the Cosserat couple modulus μ_c , or one may resort to a truly *nonlinear* coupling,
as strongly favoured in Neff (2004b) and Münch, Wagner, Neff (2011), in which
a linearisation would turn into classical elasticity without Cosserat effects. The
320 nonlinear coupling involves much more complicated mathematics which require
deeper insights in the analytical aspects (Neff, 2002; Neff, Münch, 2008; Neff,
Pompe, 2013).

Let us finally mention a Cosserat success story: the application of the con-
cept in the realm of plates and shells. Here, the introduction of an orthogonal
325 frame to the shells surface is most natural and is the preferred choice from an
engineering point of view. The first existence results for the geometrically non-
linear Cosserat plate model has been proposed again by Neff and subsequently
extended to shells (Neff, 2004a; Birsan, Neff, 2013).

3.2. Acoustic metamaterials and wave propagation in micromorphic continua

330 The concept of acoustic metamaterials is attracting increasingly the interest
of physicists and mechanicians. It is described and studied in many works: we
refer here *e.g.* to Engheta, Ziolkowski (2006) or Zouhdi, Ari, Vinogradov (2008).

In this field, the particular shape, geometry, size, orientation and arrange-
ment of metamaterial constitutive elements can affect the propagation of light or
335 sound waves in a not-yet-observed manner, creating material properties which
cannot be found in nature.

Particularly promising in the design of metamaterials are those with mi-
crostructures which present high-contrast in microscopic properties: these highly

heterogeneous microstructures, once homogenised, produce generalised continuum models (Alibert, Seppecher, dell’Isola, 2003; Forest, Sievert, 2006; Forest, 2009; Misra, Ching, 2013; Misra, Singh, 2013). In these metamaterials, when the size of the Representative Elementary Volume (REV) tends to zero, some of the physical micro-properties characterising the behaviour diverge, while simultaneously some others vanish, although the micro-structures remain quasi-periodical.

One has to remark that the standard homogenisation techniques need to be modified and/or generalised in order to be adapted to the process of identifying the macro-properties of metamaterials (Steinmann, Elizondo, Sunyk, 2007; Sunyk, Steinmann, 2003; Nadler, Papadopoulos, Steigmann, 2006; Misra, Singh, 2013; McBride et al., 2012; dell’Isola, Rosa, Woźniak, 1997, 1998; Andreaus, Ruta, 1998).

In literature, attention has been drawn on a particular mechanical metamaterial sub-class, which is significant to the considerations of this paper: the acoustic metamaterials. To give a hint of the possible applications of the newly designed metamaterials, we list some papers which are more relevant to our results, especially in the perspective of their extension to 2D and 3D systems. In Lee et al. (2010) a composite medium, exhibiting negative effective bulk modulus or negative effective mass density or both of them, is studied. In Kolpakovs (1985) and Xu et al. (1999) materials with negative Poisson’s ratio, named *auxetic materials*, were designed. Anisotropic versions of the so-called pentamode structures, *i.e.* having a finite bulk modulus and vanishing shear modulus, are candidates for effective control of acoustic waves (Christensen, de Abajo, 2012). In Porubov (2003) amplification of strain waves are investigated.

The papers Neff et al. (2013) and Ghiba et al. (2013) study a large class of evolution equations governing the propagation of linear waves in micromorphic or generalised continua (Placidi et al., 2013; Rosi, Giorgio, Eremeyev, 2013). A series of papers (Neff, Pauly, Witsch, 2012, 2013), which propose the mathematical bases necessary for the formulation of the new relaxed micromorphic model, are of independent interest.

370 The Lagrangian density for the relaxed micromorphic continuum in isotropic, linear-elastic case, as proposed in [Ghiba et al. \(2013\)](#) and [Neff et al. \(2013\)](#), can be introduced

$$\begin{aligned}
\mathfrak{L}(\mathbf{u}, \nabla \mathbf{u}, \mathbf{P}, \dot{\mathbf{u}}, \dot{\mathbf{P}}) &= \frac{1}{2} \rho \|\dot{\mathbf{u}}\|^2 + \frac{1}{2} \eta \|\dot{\mathbf{P}}\|^2 + \\
&- \left(\mu_e \|\text{sym}(\nabla \mathbf{u} - \mathbf{P})\|^2 + \frac{\lambda_e}{2} (\text{tr}(\nabla \mathbf{u} - \mathbf{P}))^2 + \mu_h \|\text{sym} \mathbf{P}\|^2 + \frac{\lambda_h}{2} (\text{tr} \mathbf{P})^2 + \right. \\
&\left. + \mu_c \|\text{skew}(\nabla \mathbf{u} - \mathbf{P})\|^2 + \frac{\alpha_c}{2} \|\text{Curl} \mathbf{P}\|^2 \right)
\end{aligned} \tag{23}$$

where \mathbf{u} is the displacement field and the microstrain tensor \mathbf{P} is a second order tensor which accounts for deformations associated to the medium microstructure, ρ is the density per unit of macro volume of the material, η is the micro-density and $\mu_e, \mu_h, \mu_c, \lambda_e, \lambda_h$ and α_c are elastic coefficients assumed to be constant.

It is clear that, in further investigations, the great variety of propagating waves that may exist in micromorphic or complex continua may unfold useful engineering applications, through the design of particularly tailored metamaterials with up-to-now not imagined features. The problems studied in [Neff \(2002\)](#) and [Neff, Jeong \(2009\)](#) are the mathematical basis for these developments.

We already mentioned that Bleustein ([Bleustein, 1967](#)) shows how Cosserat's model reduces to Piola's. In this sense, the results obtained from the study of wave propagation in micromorphic media intrinsically contains those of second gradient media. Introductory results on wave propagation in second gradient elastic media have shown a variety of exotic phenomena in mainly shielding or transmitting through embedded media interfaces. It has been shown that ([dell'Isola, Madeo, Placidi, 2012](#); [Placidi et al., 2013](#); [Rosi, Madeo, Guyader, 2013](#); [Rosi, Giorgio, Eremeyev, 2013](#)), for waves at frequencies sufficiently high to interact with the microstructure, the shielding or transmitting properties can be significantly enhanced. Technologically significant devices may be designed exploiting such exotic wave propagation properties, for example in the fields of vibration and acoustic passive control or stealth technology. Some prelimi-

395 nary results on the study of wave propagation in micromorphic media indicate
that, for particular sets of the constitutive parameter values, propagation of
some types of waves can be inhibited or waves that propagate without carry-
ing energy can be also observed. Such exotic frequency-dependent behaviours
are observable as bulk properties of the micromorphic medium, ignoring more
400 complicated reflection and transmission phenomena at the surfaces of material
properties discontinuity. This means that well-conceived micromorphic materi-
als may be used as exotic wave-guides which allow, depending on the envisaged
use, to filter and switch on and off some typical waves.

3.3. Functional Structural modifications and their use for designing metamate- 405 rials

In the mechanics of materials and structures the concept of “functional struc-
tural modification” has been developed as a modification of a *principal structure*,
without changing its original uses, aimed at obtaining an engineering *collateral*
purpose, generally an improvement of the behaviour (Carcattera, 2005; Car-
410 caterra, Akay, Ko, 2006; Carcattera, Akay, 2007, 2011; Altenbach, Eremeyev,
2008, 2009; Bîrsan et al., 2012).

Relevant examples of principal structures are systems for carrying loads in
space applications and industrial or space robotic arms affected by forced vi-
brations that, in absence of damping, could eventually have a destructive effect.
415 In these cases, structural modifications of the principal structures are aimed
at the addition of some elements that damp vibrations: these devices may be
e.g. arrays of piezoelectric actuators coupled with dissipative electronic circuits
(dell’Isola, Vidoli, 1998b).

In general, a structural modification is the addition of a designed new struc-
420 ture which –once coupled with the original one– will produce the desired, effi-
cient effect.

It is our opinion that multidisciplinary studies are very often fruitful and
crucial in technology advancement. On the contrary, a lost awareness in engi-
neering sciences concerns the importance of scientific knowledge in the process of

425 conceiving technological applications; interesting considerations on this subject
are in [Russo \(2004\)](#).

In this context it has to be remarked that the very interesting concepts that
motivated the papers [Carcattera, Sestieri \(1995\)](#), [Carcattera et al. \(2000\)](#), [Culla,
Sestieri, Carcattera \(2003\)](#), [Carcattera \(2005\)](#) and [Carcattera, Akay \(2007\)](#) stem
430 from the thermodynamics and statistical mechanics of irreversible systems. Al-
though the theory of mechanical vibrations is often considered far from thermo-
dynamics¹, these papers show how the concepts, that one may consider very dis-
tant, of irreversibility, Poincar recurrence time and thermodynamic equilibrium
are prolific in this context. Actually in those papers, the concept of structural
435 modification is considered together with the concept of hamiltonian system and
internal degrees of freedom: a structure is coupled with many internal extra
degrees of freedom properly designed. In this way, one can trap mechanical
vibration energy for a very long time, related to the Poincar recurrence time,
and thus construct a structure with an effective damping system.

440 Alternatively, it will be an interesting challenge to design metamaterials
whose material particles are endowed with such *energy sinks*. These sinks may
be conceived as some growing *micro-structural* damage ([dell'Isola, Woźniak,
1997a](#); [Misra, Singh, 2013](#); [Rinaldi, Lai, 2007b](#); [Rinaldi, 2013](#); [Yang, Misra,
2010, 2012](#); [Yang, Ching, Misra, 2011](#); [Auffray, Bouchet, Brechet, 2010](#)). In
445 this case, until the evolution of micro-damages do not affect the macroscopic
material behaviour, the applied loads is sustained, as the design requires. Of
course a *micro-structural* yield criterion has to defined to assure the *macro-
structural* integrity of the metamaterial. This topic is further discussed in some
of the following sections.

¹Very often mechanical engineers specialise their skills, alternatively, focusing on or simply
ignoring thermodynamics.

450 4. Smart Structures with distributed control

A class of metamaterials is represented by controlled smart structures, recently introduced to optimise the dissipation of mechanical vibration energy. The purpose is to *tune* an electronic circuit network in such a way that the electric eigenfrequencies always coincide with the mechanical eigenfrequencies
455 of the structural member to be damped.

This process is based on the known equivalence concept between structural members and *analogue circuits*. The investigations in this field were developed in the period 1940-1970 for another engineering application, *i.e.* the design of analogue computers: the knowledge acquired in that field can be exploited with
460 these other purposes.

In [dell'Isola, Vidoli \(1998a,b\)](#), [Vidoli, dell'Isola \(2000, 2001\)](#), [Andreaus, dell'Isola, Porfiri \(2004\)](#), [Maurini, dell'Isola, Del Vescovo \(2004\)](#), [Maurini, Pouget, dell'Isola \(2004, 2006\)](#), [Porfiri, dell'Isola, Santini \(2005\)](#) and [Giorgio, Culla, Del Vescovo \(2009\)](#) the piezoelectric transduction is applied to damp vibrating shells
465 or beams by means of a multimodal, passive control, obtained designing and coupling a distributed electronic circuit with exactly the same evolution equations as those pertaining the structural member.

These metamaterials are based on the following concept: the dynamic evolution of the structural members is linked via piezoelectric coupling terms, whose
470 mathematical structure is that of gyroscopic coupling, to the dynamic evolution of the micro-structure parameter. The latter is physically associated to observable electric potentials of a designed electronic circuit network, whose characteristics can be theoretically determined and physically realised. Evidently, the quality of precision, design and construction of electronic devices
475 cannot be paralleled by mechanical ones.

It is reasonable to assume that the Lagrangian density of the homogenised

piezo-composite plate is (Alessandroni et al., 2005)

$$\begin{aligned} \mathfrak{L}(u, \dot{u}, \dot{\psi}) = & \frac{1}{2} \rho_t \dot{u}^2 + \frac{1}{2} c \dot{\psi}^2 - g \dot{\psi} \left(\frac{\partial^2 u}{\partial x_1^2} + \frac{\partial^2 u}{\partial x_2^2} \right) + \\ & - \frac{1}{2} S_t \left[\left(\frac{\partial^2 u}{\partial x_1^2} \right)^2 + \left(\frac{\partial^2 u}{\partial x_2^2} \right)^2 + 2\nu_t \frac{\partial^2 u}{\partial x_1^2} \frac{\partial^2 u}{\partial x_2^2} + 2(1 - \nu_t) \frac{\partial^2 u}{\partial x_1 \partial x_2} \right] \end{aligned} \quad (24)$$

in which ρ_t is the effective mass per unit surface, S_t is the effective bending stiffness, ν_t is the effective Poisson ratio, c is the effective capacitance per unit surface, g is the effective piezoelectric coupling and u is the transversal displacement.

The metamaterial is globally behaving as an electromechanical wave-guide where the electric part is an internal resonator coupled to an oscillator of the mechanical subsystem.

From a purely mathematical point of view, one observes the following circumstances: i) the vibration spectrum of both the mechanical structure and its electric counterpart are exactly the same and ii) the electric system is thought as a *mirror* system whose evolving parameter is the micro-structural kinematic descriptor. Hence, piezoelectromechanical structures are particular micro-structured continua of the kind studied *e.g.* by Toupin, Eringen and Mindlin (Toupin, 1962, 1964; Eringen, 1999, 2001; Mindlin, 1964; Mindlin, Eshel, 1968).

Since piezoelectromechanical structures are controlled systems, the microstructure is designed as an optimal controller which maximises the mechanical energy absorption and possibly dissipate it through dampers *i.e.* electric resistances.

It has to be remarked that, in the mentioned investigations, shells or more complex structures are not treated neither nonlinear cases are studied, *i.e.* only material and geometric linear, simple systems are considered. So, it could be very interesting to investigate the behaviour of piezoelectromechanical structures in the case of nonlinear and more complex structural members.

Moreover, these metamaterials present some stability and bifurcation problems, especially when follower forces are considered. In a few papers (Pignataro, Luongo, 1987; Michel, Limam, Jullien, 2000; Jamal et al., 2003; Luongo, Di

Egidio, 2005; Luongo, Romeo, 2006; Belyakov, Seyranian, Luongo, 2009; Luongo, Zulli, Piccardo, 2009; Limam et al., 2010), for cases of similar complexity, these difficulties are dealt with. A preliminary study, reported in a private communication by A. Luongo, seems to indicate that piezoelectromechanical structures are less stable, in a way not yet rigorously specified, than their original mechanical counterpart. Hence, it should be planned a series of theoretical, numerical and experimental analyses of the bifurcation of piezoelectromechanical structures, using the methods presented *e.g.* in Luongo (2001), Paolone, Vasta, Luongo (2006) and Di Egidio, Luongo, Paolone (2007), aimed at characterising or even exploiting their possible imperfections and at identifying some of their constitutive parameters. In addition, numerical problems could arise from strongly coupling systems involved in studies of metamaterials as those presented in Cazzani, Ruge (2012); Garusi, Tralli, Cazzani (2004)

4.1. *Microstructured continua as damaged body models*

Bodies with micro-cracks or other damage mechanisms can be modelled by means of either discrete methods, producing finite dimensional models, or homogenised models with extra kinematical descriptors.

Interesting results in this context can be found in Rinaldi, Lai (2007a,b), Rinaldi, Krajcinovic, Mastilovic (2007), Rinaldi et al. (2008), Rinaldi (2009), Yang, Misra (2010) and Misra, Singh (2013), where the final goal is to produce a macroscopic field theory based on the knowledge, not necessarily detailed, of the micro-structure of the mechanical system.

To model the damage mechanisms, Eringen continua (Eringen, 1999, 2001, 2002; Eringen, Suhubi, 1964a,b; Sedov, 1968, 1972; Kroner, 1968) have to be assumed with the addition of dissipative effects, *e.g.* via Hamilton-Rayleigh dissipation potentials, to take into account the irreversible phenomena involving dissipation of energy.

The phenomena of *material transformation* due to the damage evolution are similar to phase transitions (dell'Isola, Romano, 1987b; dell'Isola, Woźniak, 1997a,b; Eremeyev, Freidin, Sharipova, 2003), with the addition of irreversibility

(Cuomo, Contrafatto, 2000; Contrafatto, Cuomo, 2005; Contro, Poggi, Cazzani, 1988). Damage may be described by plastic deformation phenomena (Contrafatto, Cuomo, 2002, 2006; Forest, 2009; Ciancio, Carol, Cuomo, 2006, 2007) or by crack growth (Andreas, Baragatti, 2009).

A vibration control may be obtained by degrading part of the mechanical energy involved in some *micro-structural vibrations* by means of the dissipation associated to damage phenomena, like *e.g.* plastic deformation. This control can be fruitfully employed as long as the provoked *structural modifications* do not compromise the mechanical properties of the structure.

4.2. Metamaterials designed by species evolution

It has already happened in science that a new field of investigation has taken advantage of the parallel between *structures* existing in Nature and human designed devices.

A discussion of this deep and interesting topic is not within the scope of this review: we simply cite here the case of Cybernetics, as an exemplary one.

Exotic behaviour actually means only not-yet-studied behaviour. At present, materials that are studied and used in the engineering and technology of the XX century are *simple*, with the meaning of being sufficiently well modelled with the paradigm of Cauchy continuum mechanics.

However, those scientists who tackled the problem of studying living materials understood that specific tools, much more sophisticated than those used up to that moment, were necessary. With this respect, it is illuminating the pioneering work by Wolff (Wolff, 1892).

The problem of modelling the mechanical behaviour of growing tissues has been confronted by many researchers: in this context we refer to those belonging to two groups.

The first one addresses the problem of the bone growth and reconstruction with the insertion of a graft of artificial bio-resorbable material (Mullender, Huiskes, 1995; Madeo, Lekszycki, dell'Isola, 2011; Lekszycki, dell'Isola, 2012; Madeo et al., 2012). The second group regards the mechanical description of bio-

logical tissues, with a special emphasis on their *micro-structural* behaviour (Federico, Grillo, Herzog, 2004; Federico et al., 2005; Federico, Herzog, 2008a,b,c; Federico, Gasser, 2010; Rinaldi, 2011; Federico, Grillo, 2012; Bellini, Di Martino, Federico, 2013).

The first group of papers is based on the biological knowledge according to which both the growth and resorption of bone tissue is driven by a stimulus depending on external mechanical loads. Various models are introduced in the literature to describe how the stimulus is related to the mechanical excitation and governs bone remodelling, in a living or reconstructed tissue. While in some papers (Mullender, Huiskes, 1995) the stimulus is assumed to be affected by the local state of mechanical deformation and maybe by the its time history, there is biological evidence that also the neighbouring deformation is involved. This circumstance plays a dominant role in the phenomena of growth occurring in reconstructed bones, so needs to be considered. This is done (Madeo, Lekszycki, dell'Isola, 2011; Lekszycki, dell'Isola, 2012; Madeo et al., 2012) introducing integral operators in order to represent the stimulus S , at point \mathbf{x} and time t , as a linear functional depending on the sensor cell density d and the strain energy U :

$$S(\mathbf{x}, t) = \int_{-\infty}^t \int_{V_t} K(\mathbf{x}, \mathbf{y}, t, \tau) U(\mathbf{y}, \tau) d(\mathbf{y}, \tau) d\mathbf{y} d\tau - S_0(\mathbf{x}, t)$$

where the kernel $K(\mathbf{x}, \mathbf{y}, t, \tau)$ represents the range of influence of sensor cells in space and time and $V_t(\mathbf{x}, t)$ is the volume of the bone tissue in the current configuration; S_0 , possibly depending on the position and time, is the threshold value of stimulus associated with a biological equilibrium state for which the effect of bone resorption and synthesis are balanced. In the other words, S represents the non-local behaviour both in time and space, like in the viscoelasticity or non-local elasticity (Eringen, Edelen, 1972; Haseganu, Steigmann, 1996; Parks et al., 2008; Lehoucq, Silling, 2008). If the signal from sensor cells is assumed instantaneously transmitted, *i.e.* the transmission time scale is negligible if compared with the characteristic time of the remodelling phenomena, a simpler

assumption can be stated

$$S(\mathbf{x}, t) = \int_{V_t} k(\mathbf{x}, \mathbf{y})U(\mathbf{y}, t)d(\mathbf{y}, t)d\mathbf{y} - S_0(\mathbf{x}, t)$$

where the function $k(\mathbf{x}, \mathbf{y})$ is the reduced form of the range of influence of sensor cells.

The second group of aforesaid papers regards the models for *complex* biological tissues, considered as composite materials. For instance, some tissues have an internal structure in which a porous matrix filled with an interstitial fluid is reinforced by impermeable collagen fibres: the modelling of these systems is motivated by the need to describe the phenomena related to interstitial fluid flow in articular cartilage. For this purpose, the results in [Misra, Chang \(1993\)](#), [Quiligotti, Maugin, dell'Isola \(2003\)](#), [Sciarra, dell'Isola, Coussy \(2007\)](#), [dell'Isola, Madeo, Seppecher \(2009\)](#), [Madeo, Gavriluk \(2010\)](#), [Misra, Yang \(2010\)](#) and [Madeo et al. \(2013\)](#) are useful to model the flow of a compressible or incompressible fluid in deformable porous media. Some difficulties arise in this innovative application field of micro-structured continuum mechanics: we mention for instance, in fibre-reinforced composite materials, the problem to model the permeability both in the initial undeformed configuration and its modifications during the deformation evolution. In this context, the analysis of involved length scales is crucial, as length scale separation allows simplification in the modelling procedure. In any case, different complex homogenisation methods need to be used and very often the capillary properties of the interstitial fluid may be significant: in this case the results developed in [Gatignol, Seppecher \(1986\)](#), [Seppecher \(1987, 1988, 1989, 1993, 2001\)](#), [dell'Isola, Seppecher \(1995\)](#), [dell'Isola, Gouin, Seppecher \(1995\)](#) and [dell'Isola, Seppecher, Madeo \(2012\)](#) can be of use.

5. Some research perspectives

The hints sketched in this section are limited to some research developments in progress at the M&MoCS International Research Centre. The experimental

part of investigations, proposed or in progress, need great efforts, since the sophisticated models involved are able to predict unconventional phenomena and thus most laboratory apparatuses are not designed for them.

Great care has to be paid to the theoretical aspects of proposed investigations and their design.

5.1. *Sound and vibration control via the conception of frequency filters or enhanced damping effects*

Acoustic metamaterials can be devised employing various phenomena. For a comprehensive description of the necessary models in this context we refer to [Maugin, Metrikine \(2010\)](#).

It is opinion of the authors that the most fruitful models and effects to be exploited are those involving the *energy trapping* of macroscopic waves in microscopic degrees of freedom, *i.e.* those which describe more accurately micro-motion. The reader should note that in the present context models are preceding phenomena, as we look for materials having some peculiar phenomena: this is the commonly accepted point of view when dealing with metamaterials.

The results described in [Narisetti, Ruzzene, Leamy \(2011, 2012\)](#), [Manktelow, Leamy, Ruzzene \(2013a\)](#) and [Reccia, Cazzani, Cecchi \(2012\)](#) are a useful starting point to enclose non-linearities. Multiple time-scale analyses ([Luongo, Paolone, Di Egidio, 2003](#); [Luongo, Di Egidio, 2005](#)) can be used to design wave modulations with energy transfer among vibration modes, the so-called *energy spillover*, aimed at an effective dissipation. In this case, the active degrees of freedom are those described by the micro-structural kinematical descriptors.

It is clear that, due to the coupling phenomena involving the micro-structure and thank to non-linearities, it is possible to design metamaterials in which there are gaps in wave propagation for selected frequency bands.

On the other hand, in [Ghiba et al. \(2013\)](#) and [Neff et al. \(2013\)](#) it is described a behaviour which is somewhat surprising: for a *singular* kind of linear micro-structured continuum, not admissible according to Mindlin, it is possible to choose the constitutive parameter values in order to obtain even wide

frequency wave propagation gaps. The novelty of this result is twofold: i) it seems that non-linearities are not required to achieve such gaps ii) the mathematical well-posedness, presented by the authors, indicates that the implementation of these metamaterials is highly feasible. Micro-structured continua and their physical feasibility deserve specific investigations, also by means of suitable electronic waveguides. The aforementioned preliminary results promise a rich variety of behaviour for Mindlin-type materials which could provide amazing developments.

Other investigations concerns the invention of metamaterials undergoing phase transitions when solicited by a proper mechanical action: they are named *thixotropic materials* (Barnes, 1997). Metamaterial undergoing solid-solid phase transitions could be used to reduce obnoxious mechanical vibrations, in the design of acoustic noise shields: the mechanical energy associated with the vibrations causes an endo-energetic phase transition, producing a dissipative effect (dell’Isola, Woźniak, 1997b; Yermeyev, Freidin, Sharipova, 2007).

Of course, in the description of these phenomena, strong non-linearities and non-convexities commonly occur and mathematical formulation could require higher gradient or micro-structured continua.

Efficient and volume dissipation effects, occurring in porous deformable solids, are an important class of phenomena (Sciarra, dell’Isola, Hutter, 2001; Quiligotti, Maugin, dell’Isola, 2002, 2003; dell’Isola, Guarascio, Hutter, 2000; Altenbach, Eremeyev, 2009). An interesting case takes place when the porous material is partially saturated with compressible fluid whose deformation-induced viscous flow causes energy dissipation (Madeo, dell’Isola, Darve, 2013). The fluid can be totally or partially trapped in the pores, with effects linked to the tortuosity (dell’Isola, Rosa, Woźniak, 1997, 1998; dell’Isola, Hutter, 1998; Sciarra, dell’Isola, Hutter, 2001; Madeo, Gavriluk, 2010; Madeo et al., 2013; Rosi, Madeo, Guyader, 2013). The design of metamaterials with fluid inclusions, completely or partially interconnected, or totally or partially isolated, with possibly channel opening mechanisms which dissipate energy, is really promising: slow and fast Biot-type waves may enhance the effects of wave propagation lack in

multiple frequency ranges, as already described.

655 *5.2. Conception of noise shields*

The design of *noise shields* through metamaterial characteristics is related to the subject of section 5.1.

Shields are usually modelled by means of bi-dimensional continua. The theoretical analysis of bi-dimensional continua endowed with micro-structure
660 has recently received a great impulse: we refer to the results in Neff (2004a, 2007) and Neff, Chelmiński (2007) for Cosserat shells and in Eremeyev, Zubov (2007), Eremeyev, Altenbach, Morozov (2009) and Eremeyev, Pietraszkiewicz (2011) for micro-structured shells in which phase transition may occur.

These shells are designed with properties capable to stop noise: generalising
665 some results already presented (Madeo, Gavrilyuk, 2010; Madeo et al., 2013; dell'Isola, Madeo, Placidi, 2012; Rosi, Madeo, Guyader, 2013; Rosi, Giorgio, Eremeyev, 2013; Placidi et al., 2013) one can expect to get important technological applications. Again, the key idea is *trapping* vibration energy in the internal degrees of freedom, *i.e.* those of the micro-structured shells.

Another class metamaterials may spring up from the comparative analysis
670 between the pre-stressed microstructured shells in Altenbach, Eremeyev (2009, 2010), Altenbach, Eremeyev, Morozov (2009, 2010, 2012) and Altenbach, Eremeyev, Lebedev (2011), and those involving shells with phase transitions in Eremeyev, Pietraszkiewicz (2004, 2006), Eremeyev, Zubov (2007), Pietraszkiewicz,
675 Eremeyev, Konopinska (2007) and Eremeyev, Lebedev (2013). The analysis performed in Placidi et al. (2013) implies that the interfacial mechanical properties may have very interesting and effective benefits on wave transmission and reflection: therefore one can expect that pre-stressed shells, maybe undergoing phase transitions, are efficient noise shields in a wide range of frequencies and
680 amplitudes.

Dissipative contact phenomena involving impact (Cuomo, Ventura, 1998; Andraeus, Placidi, Rega, 2010) or phenomena related to so-called energetic boundaries (Steigmann, Ogden, 1997; Steeb, Diebels, 2004; Steinmann, 2008;

Altenbach, Eremeyev, Lebedev, 2010; Altenbach, Eremeyev, 2011; McBride et
685 al., 2011) could also be fruitful. Near future researches may involve the formu-
lation of a three-dimensional boundary value problem with boundaries charac-
terised by one or more of those surface micro-structures. The structure of these
boundary conditions may induce

- a time delay in the release of incident energy at the interface,
- 690 • a concentrated dissipation at the interface,
- a considerable increase of reflected energy, also with time delay,
- a surface trapping of incident energy with its release in different forms,
which could have non-parasitic uses,
- the origination of surface waves, involving surface displacement, surface
695 thickness variation or, more generally, surface micro-structural oscilla-
tions.

In the opinion of the authors the devices conceived up to now in general did not
try to completely exploit the synergistic effect of all previously listed boundary
effects: it seems unavoidable to use all of them simultaneously if one wants to
700 stop a large amount of energy in a very narrow space region.

Shells are surfaces always constituted by the same set of material particles
during the involved phenomena. The modelling difficulties dramatically increase
(dell'Isola, Romano, 1986, 1987a,b) when i) the interfaces must be endowed with
some material properties, *i.e.* simultaneously mass, energy, linear momentum,
705 electric charge and so on, and ii) they are constituted by different material
particles in different time instants. Actually, materials with phase transition, in
presence of mechanical vibrations, exhibit the onset of internal boundary layers
(Yeremeyev, Freidin, Sharipova, 2007; Pietraszkiewicz, Eremeyev, Konopinska,
2007; Ferretti et al., 2013), with localisation not known a priori: the free-moving
710 boundary problems that arise are also very difficult to solve, but may produce
another effective method for controlling the energy transfer in metamaterials.

5.3. *Metamaterials self-limiting and self-detecting effects of damage*

Damages in materials are often considered as a negative byproduct of motion or external actions. In our opinion this is not always the case, as damaging
715 phenomena, when suitably controlled, may have a positive role in conception of novel engineering devices: one can accept to sacrifice a part of mechanical resistance in order to limit the dynamical effects on a structure. This sacrifice is even more effective if the structure is endowed with a self-healing or self-limiting control. One of the most challenging fields which open to pioneering
720 investigations is exactly the search of such kind of controls.

It has been discussed how this effect may conversely result in some positive microscopically driven damping effects, at least until the damage progress does not cause a permanent structural failure. Healing is that process, occurring in living tissues, of repairing the effects of the progress of damage. A great
725 scientific and technological challenge is the conception of self-healing materials. More modestly, one could imagine systems that are able to self-limit the damage effects and so to continue to be operative also in presence of serious damages.

Piezoelectromechanical systems, described in section 4, belong to this category. These structures, in an initial stage of crack formation in their mechanical
730 part, may continue to correctly operate if the piezoelectric transduction transform enough mechanical energy into its electrical counterpart. The range of validity of this statement needs to be investigated. In particular it has to be assessed the degree of damage

- in the mechanical structure which causes the whole system failure,
- 735 • in the transduction system which affects an effective transduction,
- in the electrical part of the wave-guide which makes the piezoelectric transduction useless.

Moreover, the systems with electric and mechanical coupling have a peculiarity: it is possible to use the efficiency and sensitivity of electronic circuits to assess,

740 with periodic electrically driven checks or even observing possible malfunctioning of the electric wave-guide, the status and progression of damage. One can easily design a system of collection and processing of signals in the electric network and interpret possible anomalies, compared with analogous results of numerical simulations, for the damage assessment.

745 *5.4. Detection of material properties in growing or reconstructed bone tissue with acoustic techniques*

There are so many similar applications of sonic or ultrasonic techniques that it is not meaningful nor useful to give references about the subject. Here, as an example, a single topic by one of the authors (Del Vescovo, Fregolent, 2005, 750 2009) is cited, in which the problem of detecting damage in frescoes with non-destructive procedures is addressed.

In many papers (Madeo, Lekszycki, dell'Isola, 2011; Lekszycki, dell'Isola, 2012; Andreaus, Giorgio, Lekszycki, 2013) the growth in bone tissue, possibly consequent to reconstruction with bio-resorbable materials, is studied with particular attention to determine the final bone properties. Luckily, ultrasound 755 propagation are greatly influenced by bone mechanical properties. It is also known that bone tissue in general must be modelled as a Cosserat or second gradient material (Buechner, Lakes, 2003; Madeo et al., 2013) and so it can be regarded as a metamaterial even before reconstruction with grafted metamaterials. 760

For instance, the initial discontinuity surface, between the existing bone tissue and the bio-resorbable material used as a scaffold for tissue growth, could persist at the end of the remodelling process. This interface could be modelled with material properties, the techniques in dell'Isola, Romano (1986, 1987a,b) 765 and dell'Isola, Kosinski (1993) are a possibility, and greatly influences the transmission and reflection of mechanical waves: it is therefore possible to devise methods to determine the properties of the *metamaterial* resulting at the end of the complex remodelling process; this metamaterial can be described by using the phenomena in Placidi et al. (2013) or in Madeo et al. (2013), where in

770 the latter the effects of fluid flow in a deformable porous matrix are taken into
account (it seems that bone interstitial fluids play an important role in bone
growth processes, see section 5.5).

5.5. *Optimal design techniques for bone reconstruction*

Present models are insufficient to describe the bone remodelling and it is
775 really challenging to add all relevant features necessary to attain a reasonably
detailed characterisation of these phenomena.

The difficulty resides in weighing the relative importance of factors whose
role in these phenomena is just qualitatively known; efforts, in this direction
and for specific situations, are described *e.g.* in [Andreaus, Colloca \(2009\)](#).

780 Indeed, it is clear that:

- in reconstructed bones, the tissue may be constituted by a mixture of
living bone and resorbable biomaterial, the latter used as a scaffold for
the tissue growth;
- both bone and bio-resorbable material are porous with assorted sizes of
785 pores and have a solid matrix with different hierarchies of structures; thus
it is evident that micro-structured or higher gradient continuum theo-
ries are needed ([Eringen, 2002](#); [Green, Rivlin, 1964a,b,c, 1965](#); [dell’Isola,
Seppecher, 1995](#); [dell’Isola, Sciarra, Vidoli, 2009](#); [dell’Isola, Seppecher,
Madeo, 2012](#));
- porosity and average density of the porous matrix can be regarded as in-
790 dependent variables, thus requiring the introduction of a micro-structured
continuum theory;
- the interstitial fluid is filling the different networks of interconnected or
partially disconnected pores and its mechanical behaviour may widely vary
795 in different conditions, showing capillary and viscosity effects;
- a bio-resorbable material can be a metamaterial designed to favour its
final total resorption: actually, its property determination is part of the

problem to be solved;

- both the living tissue and the bio-resorbable material can be regarded as composite materials with reinforcement fibres (Cowin, 1983, 2008);
- there are probably different mechanisms controlling the resorption of bone and bio-resorbable material and the synthesis of the bone tissue: therefore it may become necessary to introduce more complicated evolution equations for the stimulus or maybe even more stimulus fields.

So, a set of integro-differential equations is to be introduced, possibly with time-delay effects, which takes into account the aspects describing the global growth and remodelling phenomena.

Moreover, the clinical requirements are clear:

- the reconstructed bone needs to resemble the natural bone as close as possible; therefore in principle, the bio-resorbable material should be completely resorbed at the end of the process and, during the resorption-remodelling process, cavities should be avoided since they prevent the formation of new bone tissue;
- remodelling and reformation process should last a reasonable period of time and the mechanical stability of the system must be continuously assured.

At this stage, an optimal problem for bone implant design may be knowingly formulated. It consists in i) defining the characteristics, like initial mass and geometrical positioning of the bio-resorbable material for bone reconstruction, which satisfy the previously listed conditions and ii) minimising the time necessary to reach the target bio-mechanical properties of the remodelled bone. A similar problem is addressed in [Andreaus et al. \(2011\)](#).

A multidisciplinary research group is required for the necessary skills: the numerical modelling demands the formulation of non-standard multiphysics codes, possibly with free-moving boundary problems, involving evolution of a

sharp separation between regions with different properties (dell’Isola, Romano, 1987a,b; Eremeyev, Freidin, Sharipova, 2003), in which the constitutive equations are part of the unknown fields to be determined.

5.6. Modelling of capillary properties in biological tissue with narrow channels.

830 Mechanosensing and the related stimulus for tissue growth seem to be influenced by interstitial fluid flow in the narrow channel network present in many biological tissues (Madeo, Lekszycki, dell’Isola, 2011; Lekszycki, dell’Isola, 2012; Madeo et al., 2012; Forest, Cordero, Busso, 2011). The modalities of this flow depend on the fluid characteristics and capillary properties of the fluid-channel
835 interface.

 In the authors’ opinion it is therefore very important to add to the models presented in Federico, Herzog (2008a,c) and Federico, Grillo (2012) the features necessary for a correct description of these phenomena (Seppecher, 1996a,b, 2002).

840 For living tissues, the results in Madeo, dell’Isola, Darve (2013) may be extended to introduce the concept of interfacial energy density in a REV: the target is a macroscopic model which takes into account wettability of micro-channels and density of transported solutes, yet in a simplified way.

 Moreover, special attention should be paid to the role of Brinkman dissipation (dell’Isola, Madeo, Seppecher, 2009; Giusteri, Marzocchi, Musesti, 2011; Giusteri, 2013) in the mechanically driven stimulus for the growth of living tissues. Although the phenomena involved in the mechanosensing are not yet completely understood, the influence of higher gradients of velocity field is widely asserted.

850 Finally, to describe the evolution of the stimulus, it is clearly convenient to adopt equations for which optimised numerical codes are already available: the integral operators up-to-now introduced to calculate the stimulus (cited in section 4.2) have implied considerable difficulties especially with regard to the computational burden.

855 **6. Conclusions**

Classical field theories are considered nowadays as a nearly sterile research activity. Instead –in the authors’ opinion– the most recent developments, not only those in the very limited part of the literature explored here, prove that field theories still are fertile tools to solve many scientific problems and to put
860 into effect promising technological applications.

The assumptions, which usually are considered to be immovable paradigms of continuum mechanics, conversely seem to have a much more restricted applicability and their removal open unexpected scientific possibilities towards technological innovations. Many new phenomena, with very interesting possibilities
865 of applications, simply wait to be observed and understood.

A remark is here pertinent: the theories of continua with micro-structures are indeed very old, as it seems they were formulated by Piola in a pristine form. However, they were not extensively used in the applications: this circumstance has erroneously been interpreted as a sign of their lack of efficacy or their
870 restricted applicability.

On the contrary, in the opinion of the authors, they were not used simply because the exercises and problems formulated in their framework have presented up to now insurmountable technical difficulties.

Nowadays the tools of numerical analysis, coupled with very versatile software packages and powerful computers, allow for the easiest implementation of
875 non-standard mathematical models, as never experienced before.

This is the historical moment where non-standard continuum models should find their fastest development.

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