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To cite this article: Lorenzo Melchiorri *et al* 2022 *J. Phys.: Conf. Ser.* **2177** 012003

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# Three-dimensional MHD flow in moderate change ratio orifice

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**Abstract.** In fusion reactor blanket design, liquid metals are attractive working fluids since it is possible to combine in a single fluid the functions of coolant, tritium carrier and breeder. These electrically conductive fluids flow in the presence of a strong magnetic field, inducing the appearance of Lorentz forces and magnetohydrodynamic MHD effects. Increased pressure loss, particularly in complex geometry elements, is a critical point for blanket design. The MHD flow through an orifice plate made by electroconductive walls ( $c = 0.01 \div 0.1$ ) has been analysed in this paper using ANSYS CFX in the range  $Re = 108$ , and  $Ha = 0 \div 300$ . A wide recirculation region is detected after the flow exits the orifice, with potentially harmful consequences for efficient tritium removal. Large pressure loss occurs in the orifice due to conductive wall and non-negligible axial length. The 3D pressure drop term is characterized through a local resistance coefficient ( $k$ ) that is found to be  $k \approx 0.205$  for well conducting walls ( $c = 0.1$ ) and  $k \approx 0.063$  for poorly conducting ones ( $c = 0.01$ ).

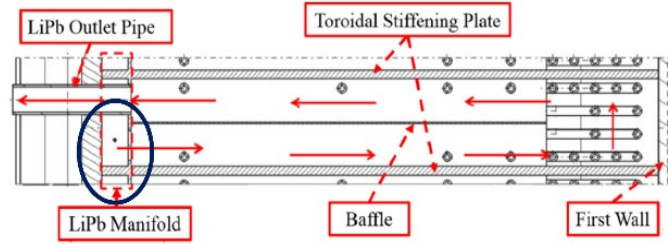
## 1. Introduction

In fusion reactor blankets, liquid metals are attractive due to the possibility to combine in a single fluid the functions of coolant, tritium carrier and breeder. These electrically conductive fluids interact with the intense magnetic field ( $\approx 4 - 8 T$ ), used to confine the plasma, causing the appearance of magnetohydrodynamic (MHD) phenomena. Increased pressure drop and flow redistribution are two effects that need to be correctly quantified to support the blanket design [1]. If the fully developed flow behavior is well understood, prediction of MHD pressure losses for developing flows in complex geometrical elements is considerably harder and far from a satisfactory theoretical explanation due to the many governing parameters involved [2]. Experiments and numerical simulations in prototypical configurations are used to estimate these losses and support the blanket design.

Sudden cross-section expansion and contraction are common hydraulic elements that exhibit complex MHD flow features like 3D currents and internal free shear layers originating from the corners [3], [4]. As such, they contribute considerably to the blanket pressure loss and, thus, an accurate estimate is of paramount importance. The most important experimental work dealing with this topic is probably the one performed by Bühler et al. [5]. Numerous simulations have been performed to characterize these components in terms of pressure loss and flow features for both insulating [6]–[9] and electrically conductive [10]–[14] rectangular ducts. A critical point is the orientation of the preferential direction for the duct expansion/contraction regarding the magnetic field, parallel variation being the most pressure loss intensive.

Considerably less studied is the simultaneous effect of a contraction followed by an expansion, as





**Figure 1:** Breeding zone cell: radial-poloidal view, orifice position highlighted [15].

occurs whenever an orifice is met by the fluid. Only two numerical works that have addressed this topic are known to the authors. Singh and Gohil analyzed an insulating duct featuring a rectangular and triangular-shaped orifice by means of a 2D model developed using OpenFOAM; a surprising choice given the inherent 3D flow nature of the chosen geometry [16]. Tassone and Caruso have performed a more detailed study in the framework of the ITER Test Blanket Module development, using a complete 3D model to represent the MHD flow at high magnetic field intensity in a mostly one-sided sudden expansion/contraction from a rectangular orifice [17].

This paper aims to contribute to the effort of characterizing the MHD flow through a rectangular orifice. The geometry considered is a sudden cross-section variation featuring a large restriction in the direction parallel to the magnetic field ( $z$ , toroidal) and a small one perpendicular to it ( $y$ , poloidal). The main channel is a rectangular duct with electrically conductive walls ( $c = 0.01 \div 0.1$ ). The problem is investigated for  $Re = 108$ , and  $Ha = 0 \div 300$ . The geometry is representative of the orifice connecting the manifold and breeding zone in the Water-Cooled Lithium Lead (WCLL) blanket [18] (Figure 1), whereas scaled-down magnetic field intensity is used to reduce the computational cost.

## 2. Problem Formulation

The MHD governing equations are obtained by the combination of the hydrodynamic set with Maxwell's one [4]. For an electrically conducting, incompressible, and viscous fluid, these equations can be written for an isothermal flow as

$$\frac{1}{N} \left( \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla \right) \mathbf{v} = -\nabla p + \frac{1}{Ha^2} \nabla^2 \mathbf{v} + \mathbf{J} \times \mathbf{B} \quad (1)$$

$$\nabla \cdot \mathbf{v} = 0, \quad \nabla \cdot \mathbf{J} = 0 \quad (2)$$

$$\mathbf{J} = -\nabla \phi + \mathbf{v} \times \mathbf{B} \quad (3)$$

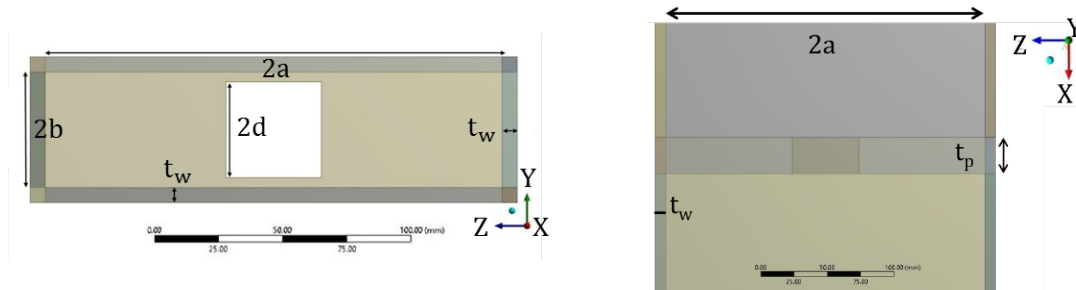
Where  $\mathbf{v}$ ,  $p$ ,  $\mathbf{J}$ ,  $\mathbf{B}$  and  $\phi$  represents velocity, pressure, current density, magnetic field, and electric potential. The variable scales are taken as described in Ref. [10]. The characteristic length scale is the duct half-width in the magnetic field direction ( $a$ ). The magnetic field is assumed to be constant and aligned to the toroidal direction,  $\mathbf{B} = B_0 \mathbf{z}$ , thus neglecting any poloidal field contribution. Using the low magnetic Reynolds number approximation,  $\mathbf{B}$  is independent by  $\mathbf{v}$ , and the set is closed with an additional equation obtained by combining Eqs. (2) and (3):

$$\nabla^2 \phi = \nabla \cdot (\mathbf{v} \times \mathbf{B}) \quad (4)$$

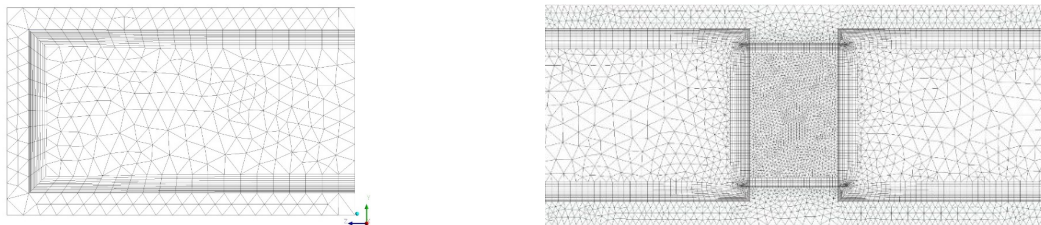
The dimensionless parameter governing the flow are the Hartmann number ( $Ha = a B_0 (\sigma \mu)^{0.5}$ ), whose square is the ratio between electromagnetic and viscous forces, and the interaction parameter ( $N = \sigma a B_0^2 \rho u_0 = Ha^2 / Re$ ), the ratio of electromagnetic and inertial forces. The problem geometry is shown in Figure 2.

The duct is characterized by an aspect ratio  $\gamma$  and is bounded by uniform thickness walls ( $t_w$ ). The square orifice is characterized by a toroidal ( $R_z$ ) and poloidal ( $R_y$ ) change ratio, as well as an axial

shape factor ( $R_x$ ). A uniform velocity  $u_0$  is assumed at the inlet, which is placed at  $X_1 = -9a$ , whereas  $p=0$  at the outlet, located at  $X_2 = 24a$ . These values are chosen to ensure a fully developed state is reached before and after the orifice. In Table 1, geometrical parameters are collected.



**Figure 2:** Problem geometry: (left) duct/orifice cross-sectional view; (right) detail of orifice, top view.



**Figure 3:** Computational grid: (left) duct mesh, (right) detail of orifice mesh, lateral view.

**Table 1:** Model geometrical parameters.

Parameter	Symbol	Value (mm)	Parameter	Symbol	Value
Duct toroidal half-length	$a$	120	Duct aspect ratio	$\gamma$	$a/b = 4$
Duct poloidal half-length	$b$	30	Toroidal change ratio	$R_z$	$a/d = 4.8$
Orifice half-width	$d$	25	Orifice axial shape factor	$R_x$	$t_p/2d = 0.6$
Wall thickness	$t_w$	8	Poloidal change ratio	$R_y$	$b/d = 1.2$
Plate radial thickness	$t_p$	30			

Since the problem features finite conductivity walls ( $c = 0.01 \div 0.1$ ), the relative conductance ratio between wall and fluid is introduced,  $c = \sigma_w t_w / (\sigma_a)$ , and Eq. (4) is a conjugated problem across the fluid and solid domain. At the fluid/solid interface, kinematic no-slip ( $\mathbf{v} = 0$ ), continuity of electric potential ( $\phi = \phi_w$ ), and normal current ( $\mathbf{J}_n = \mathbf{J}_{n,w}$ ) are the boundary conditions. On the solid external surface, the Neumann boundary condition is used ( $\partial\phi/\partial n = 0$ ) to model the surrounding dielectric medium, as well as for inlet and outlet. The physical properties of both fluid and solid are constant. For the former, it is assumed lithium-lead at 600 K [19], for the latter  $\sigma_w$  is adjusted to obtain  $c$ .

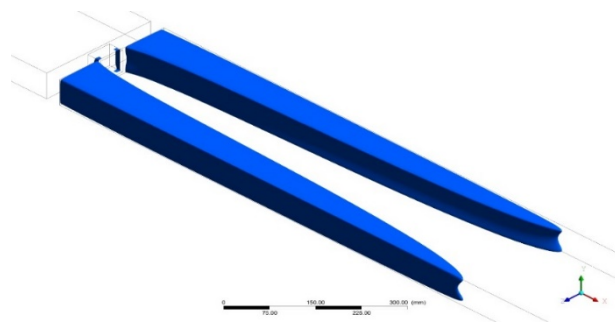
### 3. Numerical Model

The model is solved with ANSYS CFX 18.2. For all the simulations performed, high resolution advection scheme is adopted. The convergence of the solution is controlled with residuals values of mass, velocity and electric potential conservation and monitoring solution variables ( $\mathbf{v}$ ,  $\phi$ ,  $\mathbf{J}$ ) at fixed points during the run. Calculations are stopped when the root mean square residuals are lower than  $10^{-4}$  and the monitored variables remain constant. The flow is modelled as laminar and steady.

The model domain is discretized using an unstructured mesh composed by tetrahedrons in the core and solid structures, whereas prismatic elements are used to resolve the boundary layers, as shown in Figure 3. The grid is realized to include at least 2 elements in the Hartmann layer appearing at walls  $\perp \mathbf{B}$ , whose thickness is  $\delta_H = O(Ha^{-1})$ . The mesh axial resolution is increased approaching the orifice

**Table 2:** Mesh sensitivity on hydrodynamic orifice pressure drop (from Ref. [10]) versus total axial ( $N_X$ ), orifice axial ( $N_O$ ), and cross-sectional ( $N_{(Y/Z)}$ ) grid resolution.

#	$N_X$	$N_O$	$N_{(Y/Z)}$	N. of elements	$\Delta p_o$ (mPa)	$\Delta p_{\#}$ (mPa)	Error (%)
1	92	6	$96 \times 24$	223 460	6.89	8.289	20.3
2	112	12	$144 \times 36$	646 544		8.003	16.1
3	132	20	$192 \times 48$	1 361 608		7.822	13.5
4	150	30		1 480 380		7.731	12.2
5	171	45		1 575 734		7.675	11.4



**Figure 4:** Negative axial velocity iso-surfaces (recirculation regions) for OHD case.

region. A mesh sensitivity study was performed comparing the hydrodynamic orifice  $\Delta p$  calculated by the code with the one reported by Zivkovic et al. [20] for a similar configuration. An overview of the results is presented in Table 2. The grid number 4 was selected as reference for the simulations reported in Section 4. Extensive validation of the CFX electromagnetic model has been performed in the past for pressure-driven flows in finite conductivity ducts. Details can be found in Refs. [11], [12], [15].

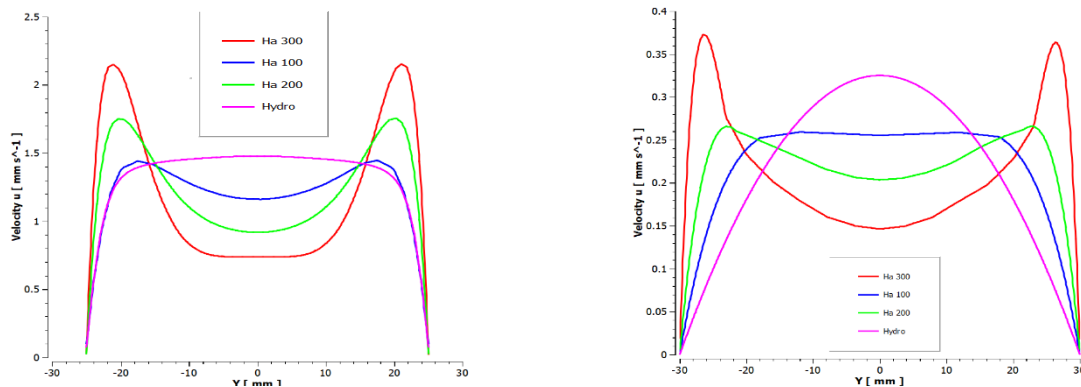
#### 4. Results and Discussion

Ordinary hydrodynamic (OHD) simulations are performed to investigate basic flow features and as reference for MHD cases. It is found that contraction ratios  $R_z$  and  $R_y$  have a significantly different effect on the flow features. The poloidal contraction is relatively small, and it is not accompanied by relevant recirculation regions: the boundary layer reattachment is observed shortly after the orifice exit ( $L_y \approx d$ ). Conversely, the toroidal contraction affects the flow features in a more dramatic fashion. Large recirculation regions are present after the orifice (Figure 4) with maximum toroidal length  $L \approx 0.75 a$ . Reattachment points are located much further downstream compared with the poloidal contraction being observed about at  $L_z = 40d$ . Maximum velocity observed in the contraction is  $u_{Max} = 1.49 \text{ mm/s}$ , which still allows to treat the flow as laminar and steady since  $Re_o \approx 900$ . Fully developed condition is regained approximately at the axial coordinate  $L_x = 72d$ .

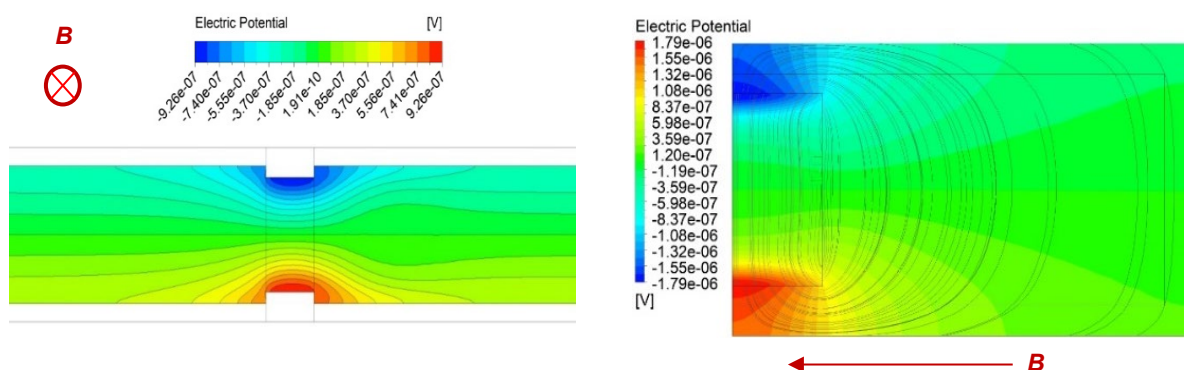
##### 4.1. MHD Results

In Figure 5, the velocity profiles along poloidal direction within the duct ( $y = \pm b$ ) and inside the orifice ( $y = \pm d$ ) are shown. For a low magnetic field, the velocity profile in the former retains a quasi-hydrodynamic shape but, for increasing  $Ha$ , the flow separates into a slug core and jets close to the

side walls. Cross-section contraction in the orifice affects the flow features more than by increasing mean velocity: M-shaped profile is observed with quicker jets and enhanced pressure losses compared with duct flow. This phenomenon is explained by the thicker Hartmann walls bounding the orifice flow,  $c = 6.13$  versus  $c = 0.1$ . A non-null velocity gradient appears along the duct axis when the flow approaches the orifice contraction that induces an electric potential difference, as shown in Figure 6. This drives 3D currents that are not confined to the cross-section (see Figure 7). These are responsible for non-axial



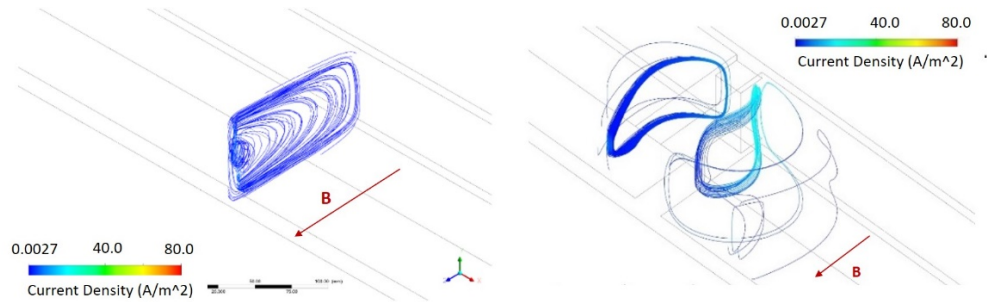
**Figure 5:** Velocity profile along  $y$ -direction (at midplane  $z = 0$ ) for increasing  $Ha$  with  $c = 0.1$  and OHD case: (left) at the orifice center ( $x=0$ ) and fully developed flow in the duct (right).



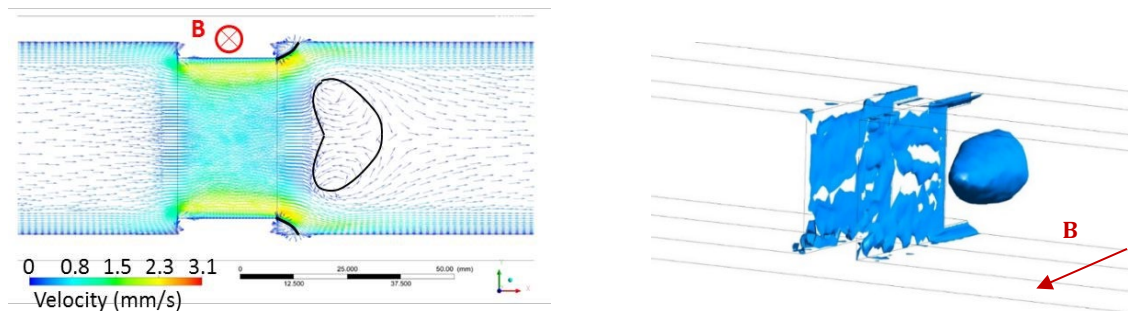
**Figure 6:** Electric potential contours and current density streamlines: left,  $z = 0$   $Ha = 100$   $c = 0.01$ ; right,  $x = 0$   $Ha = 300$   $c = 0.1$ .

Lorentz forces that causes flow redistribution and additional pressure losses. In Figure 8, it is possible to observe how the interaction between these forces, which push the fluid toward the side walls, and the flow transfer in the internal layer parallel to the magnetic field (not shown) causes core flow reversal at the duct exit. This phenomenon seems to be characteristic of the asymmetric expansion, since it is not reported by Refs. [10], [11], [17], and could lead to tritium accumulation in the manifold. It is interesting to note that a similar phenomenon was described by Rhodes et al. [8] for the sudden expansion from an insulated duct, where a pair of counter-rotating steady vortices were observed downstream of the cross-section variation. To the best of our knowledge, it is the first time that this feature is reported for electrically conductive walls. Smaller flow reversals are observed in the corners after the poloidal expansion. The recirculation region at the egress of the orifice plate appears for all the cases studied but for the lowest magnetic field intensity considered ( $Ha = 100$ ). The volume of the region is found to increase with  $c$  but decreases with  $Ha$ . The flow reversal can be explained considering that jets within the orifice are quicker than the ones in the duct and are further enhanced at the orifice exit due to the effect of the axial current: these concurring phenomena cause a flow deficit

in the duct central region and the formation of the recirculation. Secondary flow reversals are observed in the corners after the poloidal expansion whereas the Hartmann boundary layer does not undergo any separation. The flow regains fully developed state quicker than in the hydrodynamic simulation thanks to the stabilizing effect of the magnetic field. The orifice effect on the flow can be considered limited to an axial region  $L_x = \pm 5 d$ . In Table 3, recirculation zone dimensions are collected.



**Figure 7:** Current density streamlines  $Ha = 200$   $c = 0.1$ ; straight duct (left), upstream and downstream the orifice (right).



**Figure 8:** Left, velocity vector on the plane passing through the duct center ( $z=0$ ) for  $Ha = 300$  and  $c = 0.1$ . Flow reversals contoured in black. Right, 3D view of flow reversal for the same case.

**Table 3:** Downstream primary reverse flow area extension (scaled with orifice half-width  $d$ ).

		Axial	Toroidal	Poloidal
<b>Ha = 300</b>	<b>c = 0.01</b>	0.68	2.75	0.72
	<b>c = 0.1</b>	0.95	4.6	1.24
<b>Ha = 200</b>	<b>c = 0.01</b>	0.64	1.91	0.46
	<b>c = 0.1</b>	0.81	3.41	0.8

#### 4.2. Pressure Loss Analysis

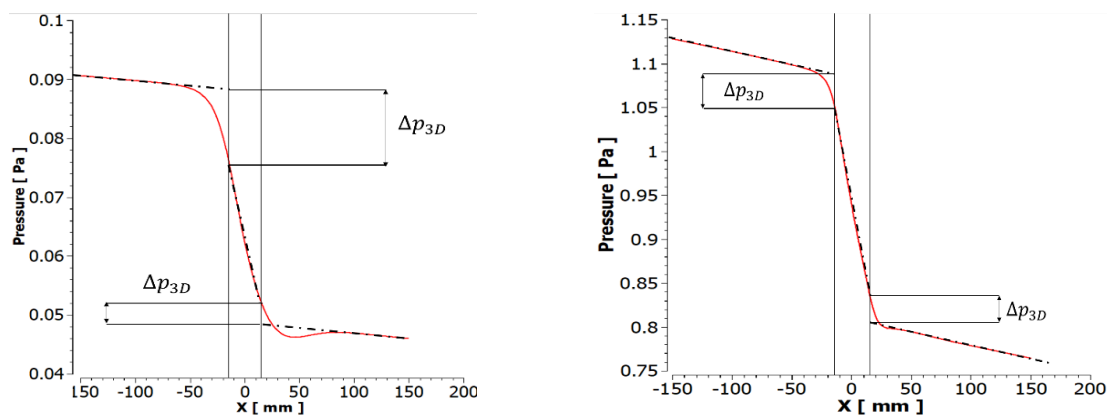
If  $Ha \gg 1$ , the pressure losses in an MHD flow are dominated by the Lorentz force. In Figure 9, the pressure profile for the flow through the orifice is sketched. The dashed lines represent the pressure profile for a fully developed flow in the main duct, downstream and upstream, and within the orifice region. For the former, it is computed from the area-averaged pressure gradient at the outlet ( $\partial_x p_1$ ), whereas the latter is calculated from the area-averaged pressure gradient at the orifice center ( $\partial_x p_2$ ). As previously noted, 2D MHD flow in the orifice features higher losses than in the duct due to a larger value of wall conductivity. A 3D pressure drop term ( $\Delta p_{3D}$ ) is associated to the flow within the orifice due to the appearance of axial currents. It is calculated from the total pressure loss in the model:  $\Delta p_{3D} = \Delta p_{tot} - 33a\partial_x p_1 - t_p\partial_x p_2$ . Results are presented in Table 4.

In general,  $\Delta p_{3D}$  is influenced by  $Ha$ ,  $N$ ,  $c$ , and geometrical parameters. For constant  $c$ , increasing  $Ha$  results in a relative  $\Delta p_{3D}$  decrease over the total one due to a weaker dependence on  $B$  compared with 2D MHD flow, for which  $\Delta p_{2D} \propto B^2$ . A similar trend is observed for increasing  $c$  at constant  $Ha$ ,

since an increment of wall conductivity affects more the intensity of the currents closing through it rather than those which are contained within the fluid. The pressure loss can be calculated with  $\Delta p_{3D} = 0.5k\sigma_0 B_0^2 d$ , where  $u_0$  and  $k$  are the orifice hydrodynamic mean velocity and local MHD resistance coefficient. Regarding this parameter, it converges to  $k \approx 0.205$  for  $c = 0.1$ , hinting to  $\Delta p_{3D}$  being determined by electromagnetic forces  $Ha = 200 \div 300$ , whereas inertial forces are still significant for  $c = 0.01$  up to  $Ha = 300$ .

## 5. Conclusions

The 3D MHD flow in an orifice with asymmetrical sudden cross-section variation has been studied



**Figure 9:** Pressure profiles along the duct centerline for the flow through the orifice: (left)  $Ha = 100$  and  $c = 0.01$ , (right)  $Ha = 300$  and  $c = 0.1$ . Vertical lines identify the orifice region. Dashed lines mark the pressure distribution for a fully developed flow in the main and orifice channel.

**Table 4:** 3D orifice pressure loss and MHD local resistance coefficient.

	c=0.01			c=0.1		
Ha	100	200	300	100	200	300
$\Delta p$ (Pa)	0.04821	0.1279	0.2374	0.1057	0.3727	1.3888
$\Delta p_{3D}$ (Pa)	0.00784	0.0107	0.0201	0.0134	0.0291	0.0669
$k$	0.221262	0.075278	0.062891	0.378225	0.204729	0.209324
$\Delta p_{3D}/\Delta p$	16.26%	8.36%	8.48 %	12.72%	7.8 %	4.82 %

using the code ANSYS CFX in the range  $Ha = 0 \div 300$  and  $c = 0.01 \div 0.1$ . The geometry considered is representative of the perforated plate connecting the manifold and breeding zone in the WCLL [15]. The flow main features are described with the most interesting one being the appearance of a wide recirculation region at the exit. The 3D pressure loss for the flow through the orifice can be estimated with  $k \approx 0.205$  for  $c = 0.1$  and  $k \approx 0.063$  for  $c = 0.01$ .

Further work is required to complete the characterization of the MHD flow through a rectangular orifice. It would be desirable to perform simulation closer to blanket conditions, i.e. featuring  $Ha \approx 10^4$ . An important point that has so far been neglected in the literature is the effect of a skewed magnetic field on the 3D loss. The effect of the orifice shape and axial length should also be investigated and its role in the onset of recirculation regions downstream of it.

**Acknowledgments** This work has been carried out within the framework of the EUROfusion Consortium and has received funding from the Euratom research and training programme 2014-2018 and 2019-2020 under grant agreement No 633053. The views and opinions expressed herein do not necessarily reflect those of the European Commission.



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