Unsupervised classification based approach for coastline extraction from Sentinel-2 imagery

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Abstract — Coastline extraction techniques from multispectral satellite images are of great interest for protection and monitoring of coastal areas. In this regard, the Sentinel-2 satellites can give a great contribution thanks to their wide coverage of the earth's surface. These images can be processed by GIS software, so as to detect the sea from all the rest. However, the traditional supervised classification requires the involvement of the operator to create suitable training sites: this approach, in addition to being associated to the operator's skill, often takes a long time to be completed. This contribution presents a study carried out on Sentinel-2 dataset and proposes the application of an unsupervised classification method, the k-means, on four different classification indices. The coastlines extracted by unsupervised classification are therefore compared with the coastline manually vectorized from the RGB composition. The results demonstrate the effectiveness of k-means for distinguishing, in the images produced by the indices application, two clusters (water / no-water) in a reduced time lapse if compared with the traditional supervised techniques.

Keywords — Unsupervised, K-means, Sentinel-2, Coastline Extraction, GIS, NDWI

I. INTRODUCTION

Today, more than half of the world's population lives in coastal regions [1]. In Italy, the population density on the coasts is more than double the national average [2]. It is therefore evident that coastal areas are particularly sensitive and require continuous monitoring. The high population density of the coastal areas makes the mapping of the coastal zones essential, such as for safe navigation [3], resource management [4], environmental protection [5], and sustainable coastal development [6] and planning [7]. In order to support these activities, it may be useful to know the position of the coastline. This operation can be carried out in several ways, including SAR [8], Lidar [9], UAV Survey [10], RTK-GPS positioning technology [11], Optical Satellite [12]. Nevertheless, the integration of present-day data with historical cartography permits to evaluate coastal changes [13, 14].

Many studies have been carried out on coastline extraction from optical satellites imagery, with both high-resolution

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satellite [15], and medium resolution [16]. However, not only the spatial resolution must be considered, but also other characteristics of the sensor, such as the spectral resolution [17], and of the satellite itself, such as the satellite revisit period [18]. Sentinel-2 satellites offer a good coverage of the Earth surface, due to their short revisiting time (5 days at the equator and 2-3 days at mid-latitudes) [19]. Giving an unambiguous definition of a coastline is complex and the subject is widely debated in the literature [20]; what can be observed from satellite imagery is the instantaneous shoreline defined as the line of separation between land and sea at the time of image acquisition. In the following we will refer to the instantaneous shoreline. By defining the coastline as the intersection of the land surface and the sea, it can be easily extracted using spectral information signed by satellite images due to the different nature (and signature) of the two neighbouring elements [20]. Some indices, such as the Normalized Difference Vegetation Index (NDVI) and the Normalized Difference Water Index (NDWI), allow to emphasize the presence of water with respect to everything else: the studies on this subject are innumerable [21-23] and present cases of both supervised [24] and unsupervised image classification [25]. The supervised classification requires the involvement of the operator to create suitable training sites: this task, in addition to being associated to the operator's skill, it often is very tedious and time-consuming [26]. Unsupervised classification can offer a viable alternative in this case, speeding up the operations and maintaining optimum efficiency.

This article presents a study carried out on Sentinel-2 dataset and proposes the application of an unsupervised classification method, the k-means, on seven different classification indices. The coastlines extracted by unsupervised classification are therefore compared with the coastline manually achieved from the RGB composition.

II. STUDY AREA AND DATASET

ESA offers Sentinel-2 satellite imagery as a completely free data source. The Copernicus Sentinel-2 mission comprises a constellation of two satellites placed in the same sun-synchronous orbit, phased at 180° to each other, namely

Sentinel-2A and Sentinel 2-B [19]. In the framework of the geographical data and their storage [27], Sentinel images are part of Copernicus geodatabase as main focus of the Risk and Recovery Mapping Service [28]. The Sentinel-2 Multispectral Instrument (MSI) samples 13 spectral bands with different spatial resolution: four bands at 10 metres, six bands at 20 metres and three bands at 60 metres. The main characteristics of Sentinel-2A satellite sensor, which products are used in this article, are reported in Table 1 [29].

Bands	Central Wavelength (nm)	Resolution (m)
B1 - Coastal Aerosol	443	60
B2 - Blue	490	10
B3 - Green	560	10
B4 - Red	665	10
B5 - Red Edge	705	20
B6 - Red Edge	740	20
B7 - Red Edge	783	20
B8 - NIR	842	10
B8A - Narrow NIR	865	20
B9 - Water Vapour	945	60
B10 - SWIR Cirrus	1375	60
B11 - SWIR	1610	20
B12 - SWIR	2190	20

 TABLE I.
 CHACTERISTIC OF SENTINEL-2A IMAGES

The study area covers a stretch of coast about 24 km long in south-eastern Sicily (Italy), east of the city of Pozzallo (Figure 1). This area has mainly sandy coasts which generally have a low vertical gradient $(1^{\circ} - 2^{\circ})$. Nearshore areas present smooth slopes with bathymetric contours running parallel to the coastline [30].



Fig. 1. Localization of the study area in the Mediterranean Sea in equirectangular projection and WGS84 geographic coordinates (EPSG: 4326).

The Sentinel-2A imagery used for the experiments were acquired in October - 29 - 2020. As reported in Figure 2, the study area is included in the following UTM/WGS84 zone 33N coordinate system: $E_1 = 486,000 \text{ m}$; $E_2 = 505,000 \text{ m}$; $N_1 = 4,059,000 \text{ m}$; $N_2 = 4,066,000 \text{ m}$.



Fig. 2. RGB composition of the Sentinel-2A images in UTM/WGS 84 plane coordinates (EPSG: 32633).

III. METHODS

A. Index Calculation

For this study 4 indices are experimented: Normalized Difference Vegetation Index (NDVI), Enhanced Vegetation Index (EVI), Normalized Difference Water Index (NDWI), Modified NDWI (MNDWI).

NDVI is typically used for the identification of vegetated areas, however it allows to easily distinguish, in addition to vegetation, two other classes: bare soil and water [31]. NDVI formula can be expressed as follow:

$$NDVI = \frac{NIR - RED}{NIR + RED}$$
(1)

EVI is an optimized vegetation index, more responsive to canopy structural variation [32]:

$$EVI = 2.5 \cdot \frac{NIR - RED}{NIR + 6 \cdot RED - 7.5 \cdot BLUE + 1}$$
(2)

NDWI is designed to enhance the presence of water, by presenting a major contrast between water and land than the one that can be obtained from NDVI. NDWI can be achieved with the following formula [33]:

$$NDWI = \frac{GREEN - NIR}{GREEN + NIR}$$
(3)

Figure 3 shows the output obtained by the application of NDWI.



Fig. 3. NDWI obtained from the Sentinel-2A images in UTM/WGS 84 plane coordinates (EPSG: 32633).

An alternative version of NDWI is the MNDWI, which replace the Green band with the Blue one [34]:

$$MNDWI = \frac{BLUE - NIR}{BLUE + NIR}$$
(4)

Another possibility to identify the coastline is to calculate ratios between bands, for example the Red-Green ratio (RGR) and NIR-Red ratio (NRR) [35]:

$$RGR = \frac{RED}{GREEN} \tag{5}$$

$$NRR = \frac{NIR}{RED}$$
(6)

Another interesting approach is based on multiple steps starting from the difference between NDVI and NDWI [36]. In this paper we want to consider the first step only, as reported in Herndon et al. [37], and we call it Difference Index (DI):

$$DI = NDVI - NDWI \tag{7}$$

B. K-Means Clustering

K-means clustering is applied to each index, extracting two clusters (water/no-water) in order to classify the images. This procedure is carried out in SAGA GIS (Version 2.3.2).

K-means is a clustering algorithm, that partitions dataset into K number of clusters by standard Euclidean distance [38]; it is an iterative method that requires to repetitively define the centre of the clusters. It starts with arbitrary positions distributed on the data cloud, and then the positions are adjusted iteratively considering the results obtained each time. The process stops when there are no more variations in terms of allocation of centres and cluster boundaries [39].

In unsupervised classification, regardless of the adopted method, the resulting classes will be indicative of the natural spectral clusters present in the data, so clusters may also not correspond to actual covers or classes of materials [40].

In fact, there are pros and cons when adopting unsupervised classification. Pros: no prior knowledge of the investigated area is required; human error is greatly reduced; the classes are necessarily spectrally homogeneous; reduction of the work time. Cons: the obtained classes do not necessarily have a physical meaning; the user has limited control over the procedure and results.

However, in this case, the two resulting clusters effectively correspond to the researched classes: water/no water. The result of K-Means clustering applied to NDWI is shown in figure 4.



Figure 4 – Result of K-Means clustering applied to NDWI: land is represented in black, while water is represented in white.

C. Accuracy Tests

Once the classification is complete, the coastlines can be extracted. In this study seven coastlines are extracted. The products are compared with a reference one (Reference Coastline – RCL), achieved by manual vectorization of the RGB composition by means of visual analysis as shown in figure 5.



Figure 5 – RCL manually achieved (in red) on RGB composition of the Sentinel-2A images in UTM/WGS 84 plane coordinates (EPSG: 32633).

To assess the efficiency of the unsupervised classification two indices are calculated. The first one, namely Accuracy Index (AI), was proposed by Zangh et al., 2013 [41], and considers the relative shortening or lengthening of the extracted coastline with respect to the reference one:

$$4I = \frac{(L'-L)}{L} \cdot 100 \tag{5}$$

where L is the actual length of the coastline (or in this case the manually achieved coastline), L' is the length of the resulting coastline.

The second index, namely Ratio Index, taken into account was developed by Maglione et al., 2014 [17], considers the deviation between the two coastlines. Particularly, if the overlap between the two lines does not occur perfectly, polygons are generated: considering their area (A), and the actual length of the coastline (L), RI is defined as follow:

$$RI = \frac{A}{L} \tag{6}$$

IV. RESULTS AND DISCUSSION

Table 2 reports the results obtained by applying AI and RI.

AI AND RI VALUES FOR THE EXTRACTED COASTLINES

9.887

3.453

Method	AI (%)	RI (m)
NDVI	28.79	6.434
EVI	29.37	8.688
NDWI	27.55	2.565
MNDWI	28.21	3.398
RGR	28.13	26.006

31.61

25.98

NRR

DI

The results show that in each case the extracted coastline presents an elongation, since AI values are always positive. The coastline that suffered less elongation is DI, with the lowest AI value (25.98 %), while NRR did provide the highest value (31.61 %). However, all the results provided by AI are very similar and no consistent difference can be seen between the coastlines.

In order to evaluate RI results the pixel size is used as the spatial unit for the accuracy assessment [42], which in this case is 10 m. All the results provided by RI are within 10 m, so they

TABLE II.

can be considered consistent with spatial resolution of the imagery. Even in this case EVI provided the worst results, labelling it as the least suitable of the indices proposed in this work for the coastline extraction. Very good results are achieved by the application of NDWI (2.565 m), as expected.

Above all we can say that the proposed approach based on unsupervised classification develops very good results.

The unsupervised classification with just two classes provides good results, as good as other techniques described in literature [12, 43, 44]. In particular, k-means clustering is very suitable when applied to the indices investigated in this article. Nevertheless, unsupervised classification allows to achieve good results faster than supervised classification, since training sites are not required.

V. CONCLUSION

This article aims to analyse the results that can be achieved with unsupervised classification for coastline extraction from Sentinel-2 imagery. The attention is focused on the outputs provided by k-means clustering applied on seven different indices, which can be seen as synthetic bands. To test the products of the unsupervised classification, two indices are used to evaluate the coastlines in terms of elongation (AI) and shift (RI) from the reference coastline.

While there is no reference to evaluate AI results, the values obtained with RI can be compared with the pixel size of the Sentinel-2 bands 2, 3, 4 and 8 (10 m): in these terms the results are very encouraging, since every coastline provided RI values less than 10 m.

Finally, Sentinel-2 images provide a good support, however as a future goal, these techniques require to be tested on other kind of satellite multispectral imagery, such as the PRISMAs recently released by the Italian Space Agency (ASI).

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