



# The Belle II SVD detector

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The Silicon Vertex Detector (SVD) is one of the main detectors in the Belle II experiment at KEK, Japan. In combination with a pixel detector, the SVD determines precise decay vertices and performs low-momentum track reconstruction. The SVD ladders are being developed at several institutes. For the development of the tracking algorithm as well as the performance estimation of the ladders, beam tests for the ladders were performed. We report an overview of the SVD development, its performance measured in the beam tests, and the prospect of its assembly and commissioning until installation.

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## 1 1. Overview of SVD detector

The Belle II experiment [1] is an intensity frontier experiment whose main goal is to discover physics beyond the standard model (BSM) by indirect means. The experiment is installed at an interaction point of the SuperKEKB [2] collider at KEK (Tsukuba, Japan), which is an  $e^+ e^-$ 

- <sup>5</sup> collider operating at a center-of-mass energy near the  $\Upsilon(4S)$  resonance. The  $e^+$  and  $e^-$  beams in
- <sup>6</sup> SuperKEKB have energies of 4 and 7 GeV, respectively, with a beam crossing angle of 41.5 mrad.
- <sup>7</sup> The collider is designed to have an instantaneous luminosity of  $L = 8.0 \times 10^{35} \text{ cm}^{-2} \text{s}^{-1}$ , which
- 8 is 40 times larger than the previous KEKB collider for the Belle experiment. The detectors and
- <sup>9</sup> accelerator are being developed for the start of physics experiment in 2018.



Figure 1: The Belle II Vertex Detector (VXD), which consists of the PXD and the SVD.

In the Belle II experiment, precise determination of the decay vertex position and low-momentum 10 tracking are essential for the search of BSM physics, in particular to look for possible BSM contri-11 butions to the CP violation asymmetry in the beauty and charm sector. These tasks are performed 12 by two silicon detectors: PiXel Detector (PXD) and Silicon Vertex Detector (SVD). The combi-13 nation of these two detectors together goes by the name of the VerteX Detector (VXD). Figure 1 14 shows the 3D CAD model of the VXD. The PXD consists of DEPFET [3] pixel sensors that form 15 the inner two layers of the VXD, while the SVD comprises the outer four layers, that are equipped 16 with Double-sided Silicon Strip Detectors (DSSD). Going from inside to outside, the four SVD 17 layers are named Layer-3, 4, 5, and 6. In order to operate in the high beam background of Su-18 perKEKB [4], a short shaping time on the front-end electronics, a radiation hardness of more than 19 100 kGy are required on the SVD. Moreover, the SVD must have standalone tracking capability 20 down to a transverse momentum of 50 MeV/c. 21

The SVD consists of ladders which are arrays of DSSD modules. Layer-3, 4, 5, and 6 have 7, 10, 12, and 16 ladders cylindrically arranged around the interaction point. Figure 2 shows a cross-sectional view of the VXD and the SVD ladders. The Layer-3 ladder is straight, whereas in Layer-4, 5, and 6 the last DSSD is slanted under 11.9, 16.0, and 21.1 degree angles, respectively. The purposes of the slanted shape is to reduce overall material budget and the number of sensors, and at the same time to improve the hit quality by avoiding shallow hits with large cluster widths. The radial distance from the interaction point of the DSSD sensors are 39, 80, 115, and 140 mm



Figure 2: The Belle II VXD which consists of the PXD (blue ladders) and SVD (red ladders). Locations of diamond sensors for beam background monitor are also shown.

- for Layer-3, 4, 5, and 6, respectively. The average material budget of each layer is about 0.7% of
- the radiation length including stainless cooling pipes for the dual-phase  $CO_2$  cooling.



Figure 3: A cross section image of the DSSD sensor.

There are three types of the DSSD sensor, large and small rectangular sensors made by Hama-31 matsu Photonics K.K. (HPK) and trapezoidal ones from Micron. The rectangular and trapezoidal 32 sensors have thicknesses of 320 and 300 µm, respectively. P-strips in the sensor are in the longitu-33 dinal direction (same as the beam direction) and n-strips are in the transverse direction. The readout 34 strip pitches in p-strips are 75 (50) µm for the large (small) rectangular sensors, and 50-75 µm for 35 the trapezoidal sensors. The pitches in n-strips are 240 µm for the large rectangular and trapezoidal 36 sensors, and 160 µm for the small rectangular sensors. A cross section image of the DSSD sensor 37 is shown in Fig. 3. The sensor has intermediate strips without readout aluminum channels in both 38 p- and n-strips. 39 The front-end readout ASIC of the SVD is the APV25 chip [5], originally developed for the 40 CMS silicon tracking detector. The chip has a short shaping time of 50 ns and a good radiation 41

<sup>42</sup> hardness of over 1 MGy. Each APV25 has 128 read-out channels and dissipates a maximum of

43 0.4 W. In total, 1748 APV25 chips are implemented on the SVD.

In order to minimize the analog path length and hence capacitive noise, APV25 chips for the

<sup>45</sup> DSSDs are to be located as close as possible to the sensors. For the DSSDs on both ends of the <sup>46</sup> ladders (forward and backward), APV25 chips are located on the far end of the sensor, outside of <sup>47</sup> the detector acceptance. On the other hand, for the intermediate sensors, APV25 chips are to be <sup>48</sup> located on the sensors. A flexible circuit, which is named "ORIGAMI flex", is glued on the sensor <sup>49</sup> with an electrical and thermal isolation foam (AIREX<sup>®</sup>), and APV25 chips are mounted on the <sup>50</sup> ORIGAMI flex. Because these chips are within the detector acceptance, they are thinned down to

<sup>51</sup> 100 µm to reduce the material budget.

The heat dissipation from the APV25 chips on the SVD is absorbed with dual-phase  $CO_2$ cooling system [6]. Thin stainless tubes with an outer diameter of 1.6 mm and a thickness of 0.1 mm are brought into thermal contact with the APV25 chips with thermal-conductive sheets

 $_{55}$  (Softtherm<sup>®</sup> 86/125). The liquid-gas mixture CO<sub>2</sub> coolant with a temperature of about -20 °C

56 flows inside these tubes.

#### 57 2. SVD ladder assembly procedure and schedule

The ladder assembly is performed by several institutes. The University of Melbourne (Aus-58 tralia) assembles Layer-3 ladders. At the INFN-University of Pisa (Italy), forward and backward 59 subassemblies for Layer 4-6 are assembled. The subassemblies are shipped to HEPHY (Austria) 60 and Kavli IPMU (Japan). At HEPHY Layer-5 ladders are assembled, while at Kavli IPMU Layer-61 4 and Layer-6 ladders are assembled (Layer-4 ladders are the responsibility of the TIFR (India) 62 members). The ladders assembled at all assembly sites are critically reviewed by all other group 63 members ensuring the qualities of the assembled ladders are uniform. All the assembled ladders 64 are finally shipped to KEK where the SVD will be finally installed. 65

In all ladder assembly sites, the following quality assurance tests are performed for the assembled ladders. To check the mechanical precision, shifts of the DSSD sensors from the designed coordinates in XYZ direction are measured with an optical coordinate measurement machine (CMM). Typically the shifts are less than 150 μm. As a confirmation of the DSSD sensor functionality, the *I-V* curve is measured. To check for possible defects and to verify the overall DSSD performance,

<sup>71</sup> signal readout test of the ladders is performed with either laser pulse injection or  $\beta$ -source Sr<sup>90</sup>.



Figure 4: A produced Layer-6 ladder.

The mass production of ladders was started early 2016. Figure 4 shows a fully assembled and qualified Layer-6 ladder. The completion of the production is scheduled on November 2017.

The SVD integration at KEK is the final step to complete the SVD construction. The inters gration procedure must be safe and well established, as possible mistake can destroy all mounted <sup>76</sup> ladders at once. Now tools for a safe SVD integration are being developed. Prototypes of all nec<sup>77</sup> essary assembly tools have been produced. The preliminary procedure was reviewed by a review<sup>78</sup> committee including external members. We are planning to finalize the tools by February 2017
<sup>79</sup> and consequently start the SVD integration. We start the SVD integration before the completion of
<sup>80</sup> ladder production as we expect to have enough number of ladders produced by that time.
<sup>81</sup> The SVD construction is scheduled to be completed by December 2017. We will then start
<sup>82</sup> integration of the Belle II beam pipe, PXD, and SVD to produce the VXD. We plan to install the

<sup>83</sup> VXD into the Belle II detector around June 2018 for the Belle II physics running to start during the

<sup>84</sup> last quarter of 2018.

## **3. SVD performance study**



Figure 5: Setup of the SVD ladders in DESY beam test during January 2016. Ladders from all four layers are used in the setup.

Performance study for the SVD ladders was performed in tests with an electron beam and a 86 charged-hadron beam [7]. The charged-hadron beam test was performed at CERN during June 87 2015 with 120 GeV beam for study of Layer-5 ladder performance. The electron beam test was at 88 DESY during April 2016 with 2-5 GeV electron beam for study of ladders of all four layers. The 89 collision energy loss (dE/dx) of these 2-5 GeV electrons in the silicon sensor are about 40% larger 90 than the one of MIP particles. Figure 5 shows the SVD setup in this beam test. The four ladders 91 are aligned along a same direction and located at the same radial locations as the final geometry. 92 We combined the SVD setup with the 2-layers PXD prototype sensors and tested the VXD tracking 93 performance as well. This was the first test for the VXD tracking with the real SVD ladders. 94 The Signal-to-Noise Ratio (SNR) is defined as the cluster charge divided by the noise value of

The Signal-to-Noise Ratio (SNR) is defined as the cluster charge divided by the noise value of the strip. If the cluster width is more than 1, the noise value is estimated as the sum in quadrature of the noises of clusterized strips. Figure 6 shows the SNR distribution of a Layer-5 ladder tested at a hadron beam with an energy of 120 GeV. These plots also show the distributions of cluster widths 1, 2 and more than 2. The listed numbers in the plots are the most probable SNR values of these distributions.





## SNR Origami -z, p-side

(b) n-strip side

**Figure 6:** SNR distributions of a tested DSSD in (a) p-strips and (b) n-strips without cooling for a perpendicularly incident charged hadron beam with an energy of 120 GeV. (O-Z in the Layer-5 ladder). Histograms for cluster widths (CWs) of 1, 2, and more than 2 are shown in red, green, and blue, respectively, with fitted curves of Landau functions (convoluted with Gaussian). The most probable SNR values for these cluster widths are also shown.

Charges created by tracks traversing the sensor at the position of a read-out strip are collected on that strip and produce clusters with cluster width 1. As the charge collection efficiency of the readout strip is almost 100%, the obtained signals of cluster width 1 are similar in p- and n-strips. The noise values in n-strips are smaller than those in p-strips due to a shorter n-strip length. Hence, for cluster width 1, n-strips have larger SNR values than p-strips.

Charges created by tracks traversing the sensor at the position of an intermediate strip without 106 readout are collected on the neighboring strips and produce clusters with cluster width 2. Capac-107 itive coupling between the strips and backplane of the sensor causes charge-collection loss on the 108 intermediate strips, because this coupling to backplane is comparable to the one to neighboring 109 readout strips [8]. The loss in charge collection is larger in n-strips (about 25% loss for large HPK 110 sensor<sup>1</sup>) compared to p-strips (about 10% loss for large HPK sensor) because of smaller coupling 111 to neighboring strips in n-side due to a wider pitch. Therefore, the ratio between the most probable 112 SNR values of cluster width 1 and 2 are smaller than  $1/\sqrt{2}$ . We confirmed that the SNR values in 113 both p- and n-strips are well above 10 even for a cluster width of 2. 114

<sup>&</sup>lt;sup>1</sup>The loss is calculated with capacitance values estimated from the strip geometry.

**Table 1:** The most probable SNR values of cluster width 1 before and after CO<sub>2</sub> cooling (-20 °C) for a perpendicularly incident charged hadron beam with an energy of 120 GeV.

Most prob. SNR	before cooling	after cooling	ratio
p-strip side	18.1	21.1	1.17
n-strip side	30.9	35.1	1.14

The CO<sub>2</sub> cooling improves the SNR distribution because it cools down the APV25 chips reducing thermal noises on the chips. The resulting SNR values of the Landau peaks for the clusters width of 1 before and after the CO<sub>2</sub> cooling is listed in Table 1. In this test, the CO<sub>2</sub> coolant temperature was -20 °C. We observed more than 10% improvement in SNR due to the cooling.



Figure 7: Cluster residual distribution in (a) p-strips and (b) n-strips of the Layer-3 ladder.

In the DESY beam test, we reconstructed electron tracks using the clusterized hits on the four 119 ladders. In order to check the position resolution of the ladder in each layer, we studied distributions 120 of cluster residuals that are differences of the cluster hit positions from projected positions of 121 tracks reconstructed with other layers. Figure 7 shows the residual distributions in the Layer-3 122 ladder. We fitted the distributions with Gaussian functions. The fitted widths of the Gaussian are 123 10.4 µm in p-strips and 24.9 µm in n-strips. From simulation, track extrapolation uncertainties of 124  $\sim$  7 µm in p-strips and  $\sim$  8 µm in n-strips are estimated. Considering these uncertainties, DSSD 125 position resolutions are estimated to be 8.2 µm in p-strips and 23.6 µm in n-strips. These results 126 are consistent with our estimations from the strip pitch,  $p/2\sqrt{12}$ , where the factor 2 comes from 127 intermediate strips. 128

For the next study, we calculated the efficiency of the DSSD cluster hit for the tracks. In each position along the track projection, we derived probabilities that the cluster hits associated to the tracks reconstructed with other layers. The resulting efficiencies in the Layer-5 ladder are plotted on Fig. 8. The empty areas in the plot are known noisy channels which were masked out in the analysis and boundary of neighboring sensors. We confirmed excellent efficiencies of higher than 99% in all the layers.



**Figure 8:** DSSD hit efficiencies in (a) p-strips and (b) n-strips of the Layer-5 ladder as functions of track-projected positions.

#### **4. Radiation monitoring for beam abort**

An accidental beam background enhancement can damage the SVD. Hence the beam background must be monitored during the experiment and whenever the background gets high the beam must be immediately dumped. For that purpose, we install diamond detectors in the VXD volume. The detector uses a single crystal diamond of dimension  $4.5 \times 4.5 \times 0.5$  mm<sup>3</sup>, made via a chemical vapor deposition (CVD). The crystal has double-sided metallization made of Ti(100 nm) -Pt(120 nm) - Au(250 nm). The crystal is held in a package of dimension  $12 \times 20 \times 3.1$  mm<sup>3</sup>. We measure current on the bias line of the diamond with long high-quality cables.

The diamond detector has a number of merits for the beam background monitor. It has high radiation tolerance and good timing resolution. Moreover, the temperature dependence of signal gain in the diamond detector is small. The detector structure is rather simple and compact.

A pair of 4 diamond detectors are installed on two locations of the beam pipe around both ends of the PXD, and a pair of 6 such detectors are installed on two locations of the SVD support structure. These locations are shown in Fig. 2. In total, 20 diamond detectors are deployed in the VXD volume. In each location, the diamond detector surrounds the beam pipe isotropically so that angular distribution of the beam background can be detected.



Figure 9: Prototype of the diamond detector (inside the package).

Prototypes of the diamond detector (Fig. 9) were produced. They were tested on the SuperKEKB beam lines during SuperKEKB phase-1 commissioning without beam collisions. Figure 10 shows the detector currents in different beam size setting. With decreasing the beam size,



**Figure 10:** Detector currents in the diamond detector as a function of the beam size measured when SuperKEKB  $e^+$  beam was stored on the beam line. Three data sets in different beam currents, 160 mA (black), 360 mA (red), and 540 mA (blue), are plotted.

we can see a systematic enhancement on the detector current due to increase of the Touschek beam

background. We confirmed that the diamond detector works well as a beam background monitor.

# 156 **5.** Conclusions

The SVD is an essential detector for the Belle II experiment for precise vertex determination and low-momentum track reconstruction. It consists of four-layers of DSSD ladders. The ladder mass-production in all assembly sites has started since early 2016. The production is planned to be over by November 2017. The SVD integration with the produced ladders will be performed at KEK and be completed by December 2017.

We studied the SVD performance, especially the ladder SNR, position resolution, and cluster hit efficiency. These results show an excellent performance of the SVD with a SNR of greater than 10, position resolutions consistent with expectation, cluster hit efficiency of more than 99%.

The diamond detector for the beam background monitor in the VXD volume is also being developed. The prototype is produced and tested on the SuperKEKB beam line during the phase-1 commissioning. The result shows good sensitivity for the beam background.

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